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Co-chair : Yubai, K., Mie University, Japan

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Co-chair : Katsura, S., Keio University, Japan

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Co-chair : Kubo, R., Keio University, Japan

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Co-chair : Oboe, R., Universita di Padova, Italy

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Co-chair : Mandow, A., Universidad de Málaga, Spain

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Co-chair : Fujimoto, H., Yokohama National University, Japan

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Co-chair : Oda, N., Chitose Institute of Science and Technology, Japan

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Chair : Miyazaki, T., Nagaoka National College of Technology, Japan

Co-chair : Zhang, D., PKU-HKUST Shenzhen-Hongkong Institution, China

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Co-chair : Iwasaki, M., Nagoya Institute of Technology, Japan

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Co-chair : Kakinuma, Y., Keio University, Japan

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Advanced Mechatronics III

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Co-chair : Takahashi, S., Kagawa University, Japan

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Co-chair : Uchimura, Y., Shibaura Institute of Technology, Japan

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NF-003387	Lossy Data Compression Using FDCT for Haptic Communication	756
	Tanaka, H., Ohnishi, K.	
NF-003573	Human Support System Using Haptic Cell	762
	Yamanouchi, W., Katsura, S.	
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Co-chair : Murakami, T., Keio University, Japan

NF-000914	A Joint Angle Sensorless Grasping Control on Two-Fingered Robot Hands	774
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NF-004146 Robust Matching for Advanced Systems in Real Industry

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Hall [Swevers, J., Pipeleers, G., Diehl, M., De Schutter, J., Katholieke Universiteit Leuven, Belgium](#)

NF-004057 Pushing motion control systems to their limits using convex optimization techniques

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Hall [Yao, B., Purdue University, USA, Jiang, C., Zhejiang University, China](#)

NF-004154 Advanced Motion Control: from PID to Nonlinear Adaptive Robust Control