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<i>Ding Yuan, Feiyang Cheng, Hong Zhang</i>	
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<i>Masaki Yamaguchi, Yasuo Kaneko, Makoto Sasaki</i>	
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<i>Xuesong Shao, Yiping Yang, Ying Zhang, Wei Wang</i>	

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<i>Taku Senoo, Daiki Yoneyama, Akio Namiki, Masatoshi Ishikawa</i>	
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<i>Qiang Li, Robert Haschke, Helge Ritter, Bram Bolder</i>	
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<i>Sung Jo Kwak, Tsutomu Hasegawa, Seong Youb Chung</i>	
<a href="#">The Study of BWR Cutting Trajectory for Optimal Stockpile-Voxel Profile Design</a>	1961
<i>Maung Thi Rein Myo, Tien-Fu Lu</i>	

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<i>Daisuke Chugo, Yuki Sakaida, Sho Yokota, Kunikatsu Takase</i>	
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<i>Sahba Safavi, Ali Selk Ghafari, Ali Meghdari</i>	
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<i>Naoki Saito, Noboru Nakayama, Toshiyuki Sato</i>	
<a href="#">Gait Analysis for Designing a New Assistive Knee Brace</a>	1990
<i>Hongtao Guo, Aaron See-Long Hung, Wei-Hsin Liao, Daniel Tik-Pui Fong, Kai-Ming Chan</i>	

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*Takashi Mikanochara, Shingo Maeda, Yusuke Hara, Shuji Hashimoto*

A Wall-Climbing Robot without any Active Suction Mechanisms 2014  
*Yu Yoshida, Shugen Ma*

Compliant Track-Wheeled Climbing Robot with Transitioning Ability and High-Payload Capacity 2020  
*Giuk Lee, Kunchan Seo, Junhwan Park, Hwang Kim, Jongwon Kim, TaeWon Seo, Seokwoo Lee*

CoBoLD - A Bonding Mechanism for Modular Self-Reconfigurable Mobile Robots 2025  
*Jens Liedke, Heinz Wörn*

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*Keng Huat Koh, Kuppan Chetty RM, S. G. Ponnambalam*

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*Puwanan Chumtong, Yasushi Mae, Tomohito Takubo, Kenichi Ohara, Tatsuo Arai*

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*Jetsada Arnil, Yunyong Punsawad, Yodchanan Wongsawat*

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*Jun Xiao, Yan Zhang, Furui Xu, Jiangchuan Li*

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