2013 IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning

(ADPRL 2013)

Singapore
16-19 April 2013

IEEE Catalog Number: CFP13ADP-POD
ISBN: 978-1-4673-5924-5

TABLE OF CONTENTS

Local Stability Analysis of High-Order Recurrent Neural Networks with Multi-Step Piecewise Linear Activation Functions 1
Y. Huang, H. Zhang, D. Yang

Finite-Horizon Optimal Control Design for Uncertain Linear Discrete-time Systems 6
Q. Zhao, H. Xu, S. Jagannathan

Adaptive Optimal Control for Nonlinear Discrete-Time Systems 13
C. Qin, H. Zhang, Y. Luo

Optimal Control for a class of Nonlinear System with Controller Constraints Based on Finite-Approximation-Errors ADP Algorithm 19
R. Song, W. Xiao, Y. Luo

Finite Horizon Stochastic Optimal Control of Uncertain Linear Networked Control System 24
H. Xu, S. Jagannathan

Exponential Moving Average Q-Learning Algorithm 31
M. Awheda, H. Schwartz

Real-Time Tracking on Adaptive Critic Design With Uniformly Ultimately Bounded Condition 39
Z. Ni, X. Fang, D. Zhao, X. Xu

A Novel Approach For Constructing Basis Functions in Approximate Dynamic Programming for Feedback Control 47
J. Wang, Z. Huang, X. Xu, J. Wang

A Combined Hierarchical Reinforcement Learning Based Approach For Multi-robot Cooperative Target Searching in Complex Unknown Environments 52
Y. Cai, S. Yang, X. Xu

The Second Order Temporal Differrence Error for Sarsa (λ) 60
Q. Fu, Q. Liu, F. Xiao, G. Chen

Optimistic Planning for Continuous-Action Deterministic Systems 69
L. Buşoniu, A. Daniels, R. Munos, R. Babuška

Optimistic Planning for Belief-Augmented Markov Decision Processes 77
R. Fonteneau, L. Buşoniu, R. Munos

Optimized Look-Ahead Trees: Extensions to Large and Continuous Action Spaces 85
T. Jung, D. Ernst, F. Maes

Bias-Corrected Q-Learning to Control Max-Operator Bias in Q-Learning 93
D. Lee, B. Defourny, W. Powell

Value Function Approximation and Model Predictive Control 100
M. Zhong, M. Johnson, Y. Tassa, T. Erez, E. Todorov

Reinforcement Learning in the Game of Othello: Learning Against a Fixed Opponent and Learning from Self-Play 108
M. Ree, M. Wiering

A Reinforcement Learning Algorithm Developed to Model GenCo Strategic Bidding Behavior in Multidimensional and Continuous State and Action Spaces 116
A. Lau, S. Srinivasan, T. Reindl

Free Energy Based Policy Gradients 124
E. Theodorou, J. Najemnik, E. Todorov

Delayed Insertion and Rule Effect Moderation of Domain Knowledge for Reinforcement Learning 132
T. Teng, A. Tan

Exploring the Relationship of Reward and Punishment in Reinforcement Learning 140
R. Lowe, T. Ziemke

Analyzing Collective Behavior in Evolutionary Swarm Robotic Systems Based on an Ethological Approach 148
T. Yasuda, N. Wada, K. Ohkura, Y. Matsumura

Reinforcement Learning to Train Ms. Pac-Man Using Higher-Order Action-Relative Inputs 156
L. Bom, R. Henken, M. Wiering

A Study on the Efficiency of Learning a Robot Controller in Various Environments 164
S. Soga, I. Kobayashi

On the Coordination System for the Dimensionality-Reduced Inputs of Mario 170
H. Handa

Optimal Control for a Class of Nonlinear Systems With State Delay Based On Adaptive Dynamic Programming with e-error Bound 177
X. Lin, N. Cao, Y. Lin
An Integrated Design for Intensified Direct Heuristic Dynamic Programming 183
X. Luo, J. Si, Y. Zhou
Scalarized Multi-Objective Reinforcement Learning: Novel Design Techniques 191
K. Moffaert, M. Drugan, A. Nowé
Fault Accomodation for Complete Synchronization of Complex Neural Networks 200
Z. Wang, F. Chu, H. Liang, H. Zhang
Author Index