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Day 2: Tuesday March 7, 2017

Robust Control

Chair: Toshiharu Sugie (Kyoto University, Japan)

11:00-12:40, Room A

Schedule	No.	Title	Author(s)
11:00-11:20	5	On the Synthesis of Output Feedback Controllers for Robust D-Stability: Necessary and Sufficient LMI Conditions	Graziano Chesi (The University of Hong Kong, China)
11:20-11:40	13	Sensitivity minimization in active networks by port compensation	Mayuresh Bakshi (VIIT Pune, India), Virendra Sule (IIT Bombay, Mumbai, India), Maryam Shoejai Baghini (IIT Bombay, Mumbai, India)
11:40-12:00	39	Stability Analysis of Extended Induced Voltage Observer Used for High Speed Position Sensorless Control of Surface Permanent Magnet Synchronous Motor	Kento Yoshino (Kyushu Institute of Technology, Japan), Ravi Nath Tripathi (Kyushu Institute of Technology, Japan), Tsuyoshi Hanamoto (Kyushu Institute of Technology, Japan)
12:00-12:20	6	On the Complexity of SOS Programming: Formulas for General Cases and Exact Reductions	Graziano Chesi (The University of Hong Kong, China)
12:20-12:40	12	Robust Compensation of Discrete-Time Plants using 2 Degrees-of-freedom 2-Periodic Controller	Gurunayk Nayak (M. S. Ramaiah Institute of Technology, Bangalore, India), Sayantan Chakraborty (Jadavpur University, Kolkata, India), Sarit K. Das (Indian Institute of Technology, Kharagpur, India)

Nonlinear Systems

Chair: Hiroshi Ito (Kyushu Institute of Technology, Japan)

13:40-15:00, Room A

Schedule	No.	Title	Author(s)
13:40-14:00	17	New Interaction in Autonomous Decentralized Control Method for Future Social Systems	Seiji Miura (Hitachi, Ltd., Japan), Jun-ichi Miyakoshi (Hitachi, Ltd., Japan)
14:00-14:20	4	An Improved El-Gamal Cryptosystem based on Chaotic Synchronization	Teh-Lu Liao (National Cheng Kung University, Taiwan), Hsin-Han Tsai (National Cheng Kung University, Taiwan), Jun-Juh Yan (Shu-Te University, Taiwan)
14:20-14:40	9	Robust Fault Diagnosis in Nonlinear Technical Systems via Linear Methods	Alexey Zhirabok (Far Eastern Federal University, Russia), Alexey Shumsky (Far Eastern Federal University, Russia)
14:40-15:00	29	Studies on Synchronization Conditions of the Non-Uniform Kuramoto Model	Takayuki Shimohashi (Okayama Prefectural University, Japan), Xin Xin (Okayama Prefectural University, Japan), Shinsaku Izumi (Okayama Prefectural University, Japan), Taiga Yamasaki (Okayama Prefectural University, Japan)

MSCS Plenaries: Kimura-Award Commemorative Lecture

Chair: Toshiharu Sugie (Kyoto University, Japan)

15:40-16:20, 50th Anniversary Hall

Noboru Sakamoto (Nanzan University, Japan)

Title: Nonlinear optimal control and applications - stable manifold approach

Day 3: Wednesday March 8, 2017

ISCS Invited Talk

Chair: Shinji Hara (University of Tokyo, Japan), Co-Chair Jun-ichi Imura (Tokyo Institute of

Technology, Japan)

9:40-10:20, Room A

Hyungbo Shim (Seoul National University, Korea)

Title: Blending dynamics by strong coupling in multi-agent system

Multi-Agent and Networked Control Systems

Chair: Shinji Hara (The University of Tokyo, Japan), Co-Chair Jun-ichi Imura (Tokyo Institute of Technology, Japan)

10:20-11:20, Room A

Schedule	No.	Title	Author(s)
10:20-10:40	37	Time Averaging Consensus over	Kenta Hanada (Osaka University, Japan),
		Noisy Networks of Linear Symmetric	Takayuki Wada (Osaka University,
		Agents	Japan),Izumi Masubuchi (Kobe University,
			Japan), Toru Asai (Nagoya University,
			Japan), Yasumasa Fujisaki (Osaka
			University, Japan)
10:40-11:00	33	Decentralized Iterative Learning	Van Tuynh Pham (Chulalongkorn University,
		Control of Building Temperature	Thailand), Dinh Hoa Nguyen (Kyushu
		Control System	University, Japan), David Banjerdpongchai
			(Chulalongkorn University, Thailand)
11:00-11:20	25	Power Gain Bounds of Networked	Song Fang (City University of Hong Kong,
		Feedback Systems: An	China), Jie Chen (City University of Hong
		Information-Theoretic Approach	Kong, China), Hideaki Ishii (Tokyo Institute of
			Technology, Japan)

Control Applications I

Chair: Kenji Fujimoto (Kyoto University, Japan)

12:30-14:10, Room A

Schedule	No.	Title	Author(s)
12:30-12:50	22	Sampling Jitter Mitigation in	Viktorio Semir El Hakim (University of
		Latency-Critical State-Estimation	Twente, The Netherlands), Marco. J. G.
		Applications using Particle Filters	Bekooij (NXP Semiconductors, The

			Netherlands)
12:50-13:10	38	Constant Switching Frequency	Ravi Nath Tripathi (Kyushu Institute of
		Hysteresis Band Robust Controller	Technology, Kitakyushu, Japan), Ravikant
		for LCL Interfaced Grid Connected	Pandey (Kyushu Institute of Technology,
		PV system	Kitakyushu, Japan), Tsuyoshi Hanamoto
			(Kyushu Institute of Technology, Kitakyushu, Japan)
13:10-13:30	40	Finite Time Output Regulation of	Atif Qayyum (National University of Sciences
		Sampled Data Linear Systems	and Technology, Pakistan)
		through Impulsive Observer	
13:30-13:50	31	A Data-Driven Construction of	Chiaki Kojima (The University of Tokyo,
		Energy Functions for Power Grid	Japan), Yoshihiko Susuki (Osaka Prefecture
		Collective Behavior via	University, Japan), Aranya Chakrabortty
		Synchrophasors	(North Carolina State University, USA)
13:50-14:10	10	Maximum Throughput of Automated	Kenji Kumagai (The University of
		Guided Vehicle System by use of	Electro-Communications, Japan), Kenji
		Models of Traffic Flow Capacity and	Sawada (The University of
		Traffic Flow Consumption	Electro-Communications, Japan), Seiichi
			Shin (The University of
			Electro-Communications, Japan)

Control Applications II

Chair: Toshiyuki Ohtsuka (Kyoto University, Japan)

14:30-15:50, Room A

14.30-15.50, R00111A				
Schedule	No.	Title	Author(s)	
14:30-14:50	16	Development of the Vibration Analysis and Suppression Technology for Laser Galvanometers Based on Inertial Sensing Technology	Wen-Chuan Chen (Industrial Technology Research Institute, National Taipei University of Technology, Taiwan), Yu-Liang Hsu (Feng Chia University, Taiwan), Po-Huan Chou (Industrial Technology Research Institute, Taiwan), Hsin-Hung Lee(Industrial Technology Research Institute, Taiwan), Hsing-Cheng Chang (Feng Chia University, Taiwan), Shih-Chin Yang (National Taiwan University, Taiwan), Chin-Sheng Chen (National Taipei University of Technology, Taiwan)	
14:50-15:10	19	A Force Control of Hydraulic Arms with Unknown Bulk Modulus	Hiroki Momoshima (Shinshu University, Japan), Yusuke Nabana (Shinshu University, Japan), Satoru Sakai (Shinshu University, Japan)	
15:10-15:30	20	An EMG and Force based Control Strategy on an Upper Limb Rehabilitation Exoskeleton	Ran Tao (University of Auckland, New Zealand), Ho Shing Lo (University of Auckland, New Zealand), Sheng Quan (Shane) Xie (University of Auckland, New Zealand), Mingming Zhang (University of Auckland, New Zealand)	
15:30-15:50	7	Finding a Feasible Initial Solution of a Flatness-Based Multi-Link Manipulator Motion Planning under State and Control Constraints	Keisuke Uto (Denso IT Laboratory, Japan), Makoto Obayashi (Denso IT Laboratory, Japan), Gaku Takano (Denso IT Laboratory, Japan)	

Day 4: Thursday March 9, 2017

ISCS Invited Talk

Chair: Yasumasa Fujisaki (Osaka University, Japan)

9:00-9:40, Room A

Giacomo Como (Politecnico di Torino, Italy/Lund University, Sweden)

Title: Resilient control of dynamical flow networks

Resilient Control Systems

Chair: Yasumasa Fujisaki (Osaka University, Japan)

9:40-10:40, Room A

Schedule	No.	Title	Author(s)
9:40- 10:00	14	Wireless Networked Control	Ahmet Cetinkaya (Tokyo Institute of
		Resilient Against Jamming Attacks	Technology, Japan), Hideaki Ishii (Tokyo
		with Bounded Average Power	Institute of Technology, Japan), Tomohisa
			Hayakawa (Tokyo Institute of Technology,
			Japan)
10:00-10:20	21	An Approach for Energy	Yifan Yang (Waseda University, Japan), Wei
		Conservation in Just-In-Time	Weng (Waseda University, Japan), Shigeru
		Production	Fujimura (Waseda University, Japan)
10:20-10:40	15	Satisfiability-Based Analysis of	Tatsuhiro Tsuchiya (Osaka University,
		Cascading Failures in Power	Japan), Yasumasa Fujisaki (Osaka
		System Networks	University, Japan)

Automotive and Flight Control

Chair: Hitoshi Katayama (Shizuoka University, Japan)

11:00-12:20, Room A

Schedule	No.	Title	Author(s)
11:00-11:20	26	Likelihood-based Threshold Control	Zidan Xu (Sophia University, Japan), Yahui
		for Cyclic Variation Probability in	Zhang (Sophia University, Japan), Tielong
		Combustion Engines	Shen (Sophia University, Japan)
11:20-11:40	27	Adaptive Modified Super Twisting	Reesa Akbar (Politeknik Elektronika Negeri
		Control for a Quadrotor Helicopter	Surabaya, Indonesia), Naoki Uchiyama
		with a Nonlinear Sliding Surface	(Toyohashi University of Technology, Japan)
11:40-12:00	35	A Study on Attitude Control System	Eric Tan Kai Chiang (National Institute of
		during Deployment of Antenna of	Technology, Gunma College, Japan), Mizuki
		Ultra-Small Satellite for Observing	Ando (National Institute of Technology,
		Jupiter's Decametric Radio	Gunma College, Japan), Kentarou Kitamura
		Emission	(National Institute of Technology, Tokuyama
			College, Japan), Imai Kazumasa (National
			Institute of Technology, Kochi College,
			Japan), Nobuto Hirakoso (National Institute
			of Technology, Gunma College, Japan)
12:00-12:20	36	Composite Adaptive Control using	Shuvrangshu Jana (Indian Institute of
		Output Feedback for Micro Air	Science, Bengaluru, India), M Seetharama
		Vehicle	Bhat (Indian Institute of Science, Bengaluru, India)