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Taketoshi Kawabe

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Satoh, Naohiro		Honda R&D Co., Ltd.
Hans, Hardam		Delphi Automotive System Japan
Takahashi, Toshiharu		Delphi Automotive System Japan
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Suh, Jeeyoon	Hyundai Motor Company
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Pappalardo, Michele	Univ. of Salerno, Department of Industrial Engineering, Fis
Pellegrino, Arcangelo	Univ. of Salerno
Fiorentino, Anita	FIAT Group Automobiles, Pomigliano D'Arco (NA), Italy
Villecco, Francesco	Univ. of Salerno, Department of Industrial Engineering, Fis
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Sename, Olivier	Grenoble Inst. of Tech. / GIPSA-Lab.
Dugard, Luc	Gipsa-Lab. CNRS Grenoble
Morales-Menendez, Ruben	Tecnologico de Monterrey, Campus Monterrey
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Technical Program for Friday September 6, 2013

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Maruno, Naoki	Honda R&D Co.,Ltd. Automobiler R&D Center
Komoda, Satoru	HONDA
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Guanetti, Jacopo	Pol. di Milano
Onori, Simona	The Ohio State Univ.
Guezennec, Yann	Ohio State Univ.
Madella, Nullo	Ohio State Univ.
Saletti, Andrea	MIDAC Batteries S.p.A.
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Rizzoni, Giorgio
Fan, Guodong

Ohio State Univ.
The Ohio State Univ.

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Moro, Katsumi	Tokyo Univ. of Agriculture and Tech.
Nagai, Masao	Tokyo Univ. of Agriculture and Tech.
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Furuya, Junichi Hitachi Automotive Systems

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Peyton Jones, James Villanova Univ.
Spelina, Jill Villanova Univ.
Frey, Jesse Villanova Univ.

FrB2 Room 402

XEV and Battery Management Control (Regular Session)

Chair: Rizzo, Gianfranco Univ. of Salerno

13:30-13:50 FrB2.1

A LPV/Hinf Approach for Fuel Consumption Minimization of the PHEV with Battery Life Prolongation, pp. 378-383.

Wang, Tinghong Grenoble Inst. of Tech.
Sename, Olivier Grenoble Inst. of Tech. / GIPSA-Lab.
Martinez Molina, John J. GRENOBLE-INP, GIPSA-Lab.

13:50-14:10 FrB2.2

Optimal Energy Management Strategy Including Battery Health through Thermal Management for Hybrid Vehicles, pp. 384-389.

Miro Padovani, Thomas Univ. d'Orléans
Debert, Maxime Renault s.a.s.
Colin, Guillaume Univ. of Orléans
Chamaillard, Yann PRISME

14:10-14:30 FrB2.3

Feasibility Issues of Using Three-Phase Multilevel Converter Based Cell Balancer in Battery Management System for Xevs, pp. 390-397.

Altaf, Faisal Chalmers Univ. of Tech.
Johannesson Mårdh, Lars Chalmers
Egardt, Bo S. Chalmers Univ. of Tech.

14:30-14:50 FrB2.4

Including a Battery State of Health Model in the HEV Component Sizing and Optimal Control Problem, pp. 398-403.

Johannesson Mårdh, Lars Chalmers
Murgovski, Nikolce Chalmers Univ. of Tech.
Egardt, Bo S. Chalmers Univ. of Tech.
Gelso, Esteban R. Volvo Group Trucks Tech.
Hellgren, Jonas Volvo Tech.
Ebbesen, Soren ETH Zürich

FrB3 Room 403

Active Steering Control (Regular Session)

Chair: Fukao, Takanori Kobe Univ.

13:30-13:50 FrB3.1

Artificial Steering Feel Design for Steer-By-Wire Vehicles, pp. 404-409.

Balachandran, Avinash Stanford Univ.
Gerdes, J. Christian Stanford Univ.

13:50-14:10 FrB3.2

Improvement of Trajectory Tracking Performance in Autonomous Collision Avoidance by Steering, pp. 410-415.

Hayashi, Ryuzo Tokyo Univ. of Agriculture and Tech.
Chatporntanadul, Puwadech Tokyo Univ. of Agriculture and Tech.
Nagai, Masao Tokyo Univ. of Agriculture and Tech.

14:10-14:30 FrB3.3

Driver Assistance Algorithm for Automotive Collision Avoidance Using Optimization Feasibility, pp. 416-421.

Mukai, Masakazu	Kyushu Univ.
Kawabe, Taketoshi	Kyushu Univ.
14:30-14:50	FrB3.4
<i>Hyperbolic Distribution of All-Wheel Independent Braking Force for Cornering Vehicle</i> , pp. 422-427.	
Ji, Xuefei	Changchun Inst. of Engineering Tech.
He, Lin	Tsinghua Univ.
Wang, Wei	The Representatives Bureau of Vehicle Vessel
Meng, Aihong	Tsinghua Univ.
Zhong, Jianjun	Tsinghua Univ.
Song, Jian	Tsinghua Univ.

FrB4	Room 409
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Modelica Tools and Applications II (Invited Session)	
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Chair: Brembeck, Jonathan	DLR - SR FAZ
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13:30-13:50	FrB4.1
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<i>Application of Modelica to Development of Future New-Concept Vehicles (I)</i> , pp. 428-433.	
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Hirano, Yutaka	Toyota Motor Corp.
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13:50-14:10	FrB4.2
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<i>Detailed Powertrain Dynamics Modelling in Dymola - Modelica (I)</i> , pp. 434-439.	
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Picarelli, Alessandro	Claytex Services Ltd
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Roberts, Neil	Claytex Services Ltd
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Dempsey, Mike	Claytex Services Ltd
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14:10-14:30	FrB4.3
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<i>Integrated Simulation of an E4wd Vehicle Using Modelica (I)</i> , pp. 440-445.	
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Andreasson, Johan	Modelon
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14:30-14:50	FrB4.4
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<i>Model-Based Dynamic Optimization with OpenModelica and CasADi (I)</i> , pp. 446-451.	
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Shitahun, Alachew	Linköping Univ.
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Ruge, Vitalij	Bielefeld Univ.
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Gebre-medhin, Mahder	Linköping Univ.
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Bachmann, Bernhard	Bielefeld Univ.
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Eriksson, Lars	Linköping Univ.
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Andersson, Joel	Katholieke Univ. Leuven
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Diehl, Moritz	K.U. Leuven
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Fritzson, Peter	Linköping Univ.
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FrB5	Room 304
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Engine Powertrain I (Regular Session)	
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Chair: Ohata, Akira	Toyota Motor Corp.
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13:30-13:50	FrB5.1
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<i>Online Estimation of 3D-Torque Characteristics of Dual Clutches Using Control Oriented Models</i> , pp. 452-457.	
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Tarasow, Alex	Clausthal Univ. of Tech.
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Bohn, Christian	Clausthal Univ. of Tech.
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Wachsmuth, Guido	IAV GmbH, Ingenieurgesellschaft Auto und Verkehr
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Serway, Roland	IAV GmbH, Ingenieurgesellschaft Auto und Verkehr, Berlin, German
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13:50-14:10	FrB5.2
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<i>The Effect of Thermal Expansion in a Dry Clutch on Launch Control</i> , pp. 458-463.	
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Myklebust, Andreas	Linköping Univ.
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Eriksson, Lars	Linköping Univ.
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14:10-14:30	FrB5.3
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<i>Modeling and Simulation for the Dynamic Analysis of an Electronically Controlled Torque Coupling</i> , pp. 464-469.	
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Maroonian, Aris	JTEKT Corp.
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Tamura, Tsutomu	JTEKT Corp.
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Fuchs, Robert	JTEKT Corp.
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14:30-14:50	FrB5.4
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<i>Control Design for a Second Order Dynamic System : Two-Stage Turbocharger</i> , pp. 470-476.	
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Moulin, Philippe	IFP
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FrC1		Room 401
Powertrain Control Methodologies (Regular Session)		
Chair: Nakada, Hayato		Toyota Motor Corp.
15:20-15:40		FrC1.1
<i>Extremum Seeking Algorithm to Optimize Fuel Injection in a Hydraulic Linear Engine</i> , pp. 477-482.		
Zaseck, Kevin		Univ. of Michigan
Kolmanovsky, Ilya V.		Univ. of Michigan
Brusstar, Matthew		United States Environmental Protection Agency
15:40-16:00		FrC1.2
<i>The Electrical Dual Mass Flywheel - an Efficient Active Damping System</i> , pp. 483-488.		
Pfleghaar, Joachim		Tech. Univ. München
Lohmann, Boris		Tech. Univ. München
16:00-16:20		FrC1.3
<i>Including Drag Phases in Numerical Optimal Control of Diesel Engines</i> , pp. 489-494.		
Asprion, Jonas		Inst. for Dynamic Systems and Control, ETH Zurich
Onder, Christopher Harald		Swiss Federal Inst. of Tech. Zurich (ETH Zürich)
Guzzella, Lino		ETH Zurich
16:20-16:40		FrC1.4
<i>A Logical Dynamical Systems Approach to Modeling and Control of Residual Gas Fraction in IC Engines</i> , pp. 495-500.		
Wu, Yuhu		Harbin Univ. of Science and Tech.
Shen, Tielong		Sophia Univ.
16:40-17:00		FrC1.5
<i>Air/Fuel Ratio Estimation of SI Engine Using Higher Order Sliding Mode</i> , pp. 501-506.		
Akram, Muhammad Amin		MAJU
Bhatti, Aamer Iqbal		Muhammad Ali Jinnah Univ. Islamabad
Ahmed, Qadeer		The Ohio State Univ.
FrC2		Room 402
Energy Management Control for XEV III (Regular Session)		
Chair: Chen, Hong		Jilin Univ. Campus NanLing
15:20-15:40		FrC2.1
<i>The Seamless Gear Shifting Control for Pure Electric Vehicle with 2-Speed Inverse-AMT</i> , pp. 507-511.		
Liang, Qiong		Jilin Univ. NanLing)
Tang, Nana		Jilin Univ. NanLing)
Gao, Bingzhao		Jilin Univ.
Chen, Hong		Jilin Univ. Campus NanLing
15:40-16:00		FrC2.2
<i>Optimal Control of a Parallel Hybrid Vehicle Equipped with a Dual Electrical Storage System</i> , pp. 512-517.		
Fontaine, Clément		Univ. of Valenciennes et du Hainaut Cambrésis
Delprat, Sebastien		Univ. of Valenciennes et Hainaut Cambresis
Paganelli, Sébastien		Univ. of Valenciennes et du Hainaut Cambrésis
Guerra, Thierry Marie		Univ. of Valenciennes Hainaut-Cambresis
16:00-16:20		FrC2.3
<i>Improvement of Fuel Efficiency and Drivability Using Simple Prediction for Gear Changing</i> , pp. 518-523.		
Khodabakhshian, Mohammad		KTH Royal Inst. of Tech.
Feng, Lei		Royal Inst. of Tech. (KTH)
Wikander, Jan		KTH Royal Inst. of Tech.
16:20-16:40		FrC2.4
<i>Diagnostics and Prognostics Needs and Requirements for Electrified Vehicles Powertrains</i> , pp. 524-529.		
Cordoba Arenas, Andrea		The Ohio State Univ.
Zhang, Jiyu		OSU
Rizzoni, Giorgio		Ohio State Univ.
FrC3		Room 403

Traction and Brake Control I (Regular Session)

Chair: Li, Keqiang	Tsinghua Univ.
15:20-15:40	FrC3.1
<i>Design and Robustness Analysis of Global Chassis Controller with Respect to Parametric Uncertainty</i> , pp. 530-535.	
Bolia, Pratiksh	Univ. of Kaiserslautern
Weiskircher, Thomas	Tech. Univ. Kaiserslautern
Mueller, Steffen	Tech. Univ. of Kaiserslautern
15:40-16:00	FrC3.2
<i>Advanced Stability Control for Electric Vehicles Via a Novel Hybrid Actuator System</i> , pp. 536-541.	
Ringdorfer, Martin	Alpen-Adria Univ. Klagenfurt
Horn, Martin	Univ. of Klagenfurt
16:00-16:20	FrC3.3
<i>Regenerative Braking Optimization and Wheel Slip Control for a Vehicle with In-Wheel Motors</i> , pp. 542-547.	
Le Solliec, Guenaël	IFPEN
Chasse, Alexandre	IFP
Geamanu, Marcel-Stefan	Lab. des Signaux et Systèmes, Supélec

FrC4

Room 409

Reliability/Diagnosis (Regular Session)

Chair: Nielsen, Lars	Linköping Univ.
15:20-15:40	FrC4.1
<i>Fault Monitoring of the Electric Machine in a Hybrid Vehicle</i> , pp. 548-553.	
Sundström, Christofer	Linköping Univ.
Frisk, Erik	Linköping Univ.
Nielsen, Lars	Linköping Univ.
15:40-16:00	FrC4.2
<i>Dependability Assurance Framework Standardization for Safety-Sensitive Consumer Devices at the OMG</i> , pp. 554-555.	
Matsuno, Yutaka	Nagoya Univ.
Biggs, Geoffrey	National Inst. of Advanced Industrial Science and Tech.
Ohata, Akira	Toyota Motor Corp.
Ishizaki, Naoya	Toyota Motor Corp.
Tacuhi, Kenji	AIST
16:00-16:20	FrC4.3
<i>Design of Fault Tolerant Control System for Electric Vehicles with Steer-By-Wire and In-Wheel Motors</i> , pp. 556-561.	
Ito, Akira	DENSO Corp.
Hayakawa, Yoshikazu	Nagoya Univ.
16:20-16:40	FrC4.4
<i>Failure Modes and Effects Analysis Using Virtual Prototyping System with Microcontroller Model for Automotive Control System (I)</i> , pp. 562-563.	
Sugure, Yasuo	Hitachi, Ltd.
Ito, Yasuhiro	Hitachi, Ltd.
Nakata, Yohei	Kobe Univ.
Takeuchi, Yusuke	Kobe Univ.
Kawaguchi, Hiroshi	Kobe Univ.
Yoshimoto, Masahiko	Kobe Univ.
Oho, Shigeru	Nippon Inst. of Tech.

FrC5

Room 304

Engine Powertrain II (Regular Session)

Chair: Lino, Paolo	Pol. di Bari
15:20-15:40	FrC5.1
<i>Robust Numerical Approach to Mean-Value Modeling of Internal Combustion Engines</i> , pp. 564-569.	
Beño, Radek	Czech Tech. Univ. in Prague, Faculty of Electrical Engineering
Pachner, Daniel	Honeywell
Havlena, Vladimír	Honeywell Intl.
15:40-16:00	FrC5.2
<i>Flywheel Angular Velocity Model for Misfire and Driveline Disturbance Simulation</i> , pp. 570-575.	

Eriksson, Daniel	Linköping Univ.
Eriksson, Lars	Linköping Univ.
Frisk, Erik	Linköping Univ.
Krysanter, Mattias	Linköping Univ.

16:00-16:20 FrC5.3

Optimal Control of Internal Combustion Engine Test Benches Equipped with Hydrodynamic Dynamometers, pp. 576-581.

Passenbrunner, Thomas Ernst	Johannes Kepler Univ. Linz
Sassano, Mario	Imperial Coll. London
del Re, Luigi	Johannes Kepler Univ.

16:20-16:40 FrC5.4

Design and Simulation of Fractional-Order Controllers of Injection in CNG Engines, pp. 582-587.

Lino, Paolo	Pol. di Bari
Maione, Guido	Pol. di Bari

Technical Program for Saturday September 7, 2013

SaA1	Room 401
Cyclic Combustion Analysis and Control (Regular Session)	
Chair: Eriksson, Lars	Linköping Univ.
11:10-11:30	SaA1.1
<i>Effect of Transient Residual Gas Fraction for Gasoline Engines</i> , pp. 588-593.	
Sata, Kota	TOYOTA MOTOR Corp.
Kako, Junichi	Toyota Motor Corp.
Yang, Jun	Inst. of Electrical Engineering, Yanshan Univ.
Ohata, Akira	Toyota Motor Corp.
Shen, Tielong	Sophia Univ.
11:30-11:50	SaA1.2
<i>Statistical Model and Control of Residual Gas Mass in Gasoline Engines</i> , pp. 594-599.	
Yang, Jun	Inst. of Electrical Engineering, Yanshan Univ.
Sata, Kota	TOYOTA MOTOR Corp.
Kako, Junichi	Toyota Motor Corp.
Ohata, Akira	Toyota Motor Corp.
Shen, Tielong	Sophia Univ.
11:50-12:10	SaA1.3
<i>Cylinder Individual Feedback Control of Combustion in a Dual Fuel Engine</i> , pp. 600-605.	
Ott, Tobias	ETH Zurich
Zurbriggen, Florian	ETH Zurich
Onder, Christopher Harald	Swiss Federal Inst. of Tech. Zurich (ETH Zürich)
Guzzella, Lino	ETH Zurich
12:10-12:30	SaA1.4
<i>Modeling of the Thermal Behavior and the Diagnostic Systems of a SI Engine</i> , pp. 606-611.	
Hoppe, Matthias	RWTH Aachen
Hesseler, Frank-Josef	RWTH Aachen Univ. Inst. of Automatic Control
Brückner, Daniel	BMW Group
Missy, Stephan	BMW Group
Abel, Dirk	RWTH-Aachen Univ.
SaA2	Room 402
Traction and Brake Control II (Regular Session)	
Chair: Shino, Motoki	The Univ. of Tokyo
11:10-11:30	SaA2.1
<i>Basic Design of Electric Vehicle Motion Control System Using Single Antenna GPS Receiver</i> , pp. 612-619.	
Nguyen, Binh Minh	The Univ. of Tokyo
Alexander, Viehweider	The Univ. of Tokyo
Fujimoto, Hiroshi	The Univ. of Tokyo
Hori, Yoichi	Univ. of Tokyo
11:30-11:50	SaA2.2
<i>Modelling, Control & Implementation of an Electro-Mechanic Braking Force Actuator for HEV and EV</i> , pp. 620-625.	
Lindvai-Soos, Daniel	Alpen Adria Univ. Klagenfurt
Horn, Martin	Univ. of Klagenfurt
11:50-12:10	SaA2.3
<i>Comparison of Two Strategies for Optimal Regenerative Braking, with Their Sensitivity to Variations in Mass, Slope and Road Condition</i> , pp. 626-630.	
Boisvert, Maxime	Univ. de Sherbrooke
Micheau, Philippe	Univ. of Sherbrooke
Mammosser, Didier	Univ. de Sherbrooke
Desrochers, Alain	Univ. de Sherbrooke
12:10-12:30	SaA2.4
<i>Optimum Distribution of Lateral and Traction/braking Forces for Energy Conservation</i> , pp. 631-636.	
Nishihara, Osamu	Graduate School of Informatics, Kyoto Univ.
Higashino, Shimpei	Kyoto Univ.

SaA3	Room 403
Communication-Based Driver Assistance Systems (Regular Session)	
Chair: Omae, Manabu	Keio Univ.
11:10-11:30	SaA3.1
<i>Advanced Driver Assistant System Using Telematics</i> , pp. 637-642.	
Li, Shuguang	The Univ. of Tokyo
Yamabe, Shigeyuki	The Univ. of Tokyo
Sato, Yoichi	The Univ. of Tokyo
Suda, Yoshihiro	Univ. of Tokyo
Chandrasiri, Naiwala P.	Toyota Info Tech. Center Co. LTD
Nawa, Kazunari	Toyota Info Tech. Center Co. LTD
11:30-11:50	SaA3.2
<i>A Smartphone-Based Intelligent Vehicle System to Minimize the Possibility of Traffic Congestion Occurrence</i> , pp. 643-644.	
Koshizen, Takamasa	Honda Motor R&D Centre
11:50-12:10	SaA3.3
<i>Traffic Signal Control in an MPC Framework Using Mixed Integer Programming</i> , pp. 645-650.	
Kamal, Md. Abdus Samad	The Univ. of Tokyo
Imura, Jun-ichi	Tokyo Inst. of Tech.
Hayakawa, Tomohisa	Tokyo Inst. of Tech.
Ohata, Akira	Toyota Motor Corp.
Aihara, Kazuyuki	Univ. of Tokyo
12:10-12:30	SaA3.4
<i>The Impacts of Large Scale Electric Vehicles Charging Behaviour on Distribution System and Local Traffic System</i> , pp. 651-657.	
Luo, Yugong	Tsinghua Univ.
Zhu, Tao	Tsinghua Univ. State Key Lab. of Automotive Safety a
Cao, Kun	Tsinghua Univ. State Key Lab. of Automotive Safety a
Li, Keqiang	Tsinghua Univ.
SaA4	Room 409
Hils (Regular Session)	
Chair: Oho, Shigeru	Nippon Inst. of Tech.
11:10-11:30	SaA4.1
<i>Hardware-In-The-Loop Test of Battery Management Systems (I)</i> , pp. 658-664.	
Haupt, Hagen	dSPACE GmbH
Ploeger, Markus	dSPACE GmbH
Bracker, Jörg	dSPACE GmbH
11:30-11:50	SaA4.2
<i>Advanced Engine Simulator Integrated with Engine Rotational Hardware (I)</i> , pp. 665-670.	
Kinoshita, Sadahiro	Toukyou Denki Univ.
Hoshino, Daiki	Tokyo Denki Univ.
Yanagi, Yuta	Tokyo Denki Univ.
Ishikawa, Jun	Tokyo Denki Univ.
Kamamichi, Norihiro	Tokyo Denki Univ.
Yamakita, Masaki	Tokyo Inst. of Tech.
Ohata, Akira	Toyota Motor Corp.
Furuta, Katsuhisa	Tokyo Denki Univ.
11:50-12:10	SaA4.3
<i>Efficient Testing of Controller Influenced Vehicle Dynamics</i> , pp. 671-676.	
Peperhowe, Michael	dSPACE GmbH
Haupt, Hagen	dSPACE GmbH
Liem, Kusnadi	dSPACE GmbH
Schindler, Wolfgang	Daimler AG
12:10-12:30	SaA4.4
<i>Real-Time Models of Hybrid Electric Vehicle Powertrains</i> , pp. 677-682.	
Geng, Stefan	Ostwestfalen-Lippe - Univ. of Applied Science
Schulte, Thomas	Univ. of Applied Science - OWL

12:30-12:50	SaA4.5
<i>Hardware-In-The-Loop Test Rig for Integrated Vehicle Control Systems</i> , pp. 683-688.	
Heidrich, Lukas	Ilmenau Univ. of Tech.
Shyrokau, Barys	Nanyang Tech. Univ.
Savitski, Dzmitry	Ilmenau Univ. of Tech.
Ivanov, Valentin	Ilmenau Univ. of Tech.
Augsburg, Klaus	Tech. Univ. Ilmenau
Wang, Danwei	Nanyang Tech. Univ.

SaA5	Room 304
Engine Powertrain III (Regular Session)	

Chair: Harada, Shingo	Mazda Motor Corp.
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11:10-11:30	SaA5.1
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Driving Cycle Adaption and Design Based on Mean Tractive Force, pp. 689-694.

Nyberg, Peter	Linköping Univ.
Frisk, Erik	Linköping Univ.
Nielsen, Lars	Linköping Univ.

11:30-11:50	SaA5.2
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Global Dynamic Modeling for Gasoline Engine, pp. 695-699.

Shimojo, Kanako	Honda R&D Co.,Ltd. Automobile R&D Center
Kitamura, Yasutaka	Honda R&D Co
Sato, Masahiro	Honda R&D Co.,Ltd.
Vogels, Marie-Sophie	AVL List GmbH
Reumueller, Markus	AVL List GmbH
Lackner, Lukas	AVL List GmbH

11:50-12:10	SaA5.3
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A Torque Demand Strategy of IC Engines for Fuel Consumption Improvement Using Traffic Information, pp. 700-705.

Kang, Mingxin	Sophia Univ.
Shen, Tielong	Sophia Univ.

12:10-12:30	SaA5.4
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Development of Control Technology for I-ELOOP, pp. 706-710.

Kume, Akitomo	Mazda Motor Corp.
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SaB1	Room 401
Diesel Engine Control (Regular Session)	

Chair: Matsunaga, Akio	Toyota Motor Corp.
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14:00-14:20	SaB1.1
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Integrated Emission Management for Cost Optimal EGR-SCR Balancing in Diesels, pp. 711-716.

Willems, Frank	Eindhoven Univ. of Tech.
Mentink, Paul	TNO Automotive
Kupper, Frank	Eindhoven Univ. of Tech.
Van den Eijnden, Edwin	TNO Automotive

14:20-14:40	SaB1.2
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Robust Common Rail Pressure Control Algorithm for Light-Duty Diesel Engines, pp. 717-722.

Hong, Seungwoo	Hanyang Univ.
Shin, Jaewook	Hanyang Univ.
Park, Inseok	Hanyang Univ. Department of automotive engineering, ACE La
Sunwoo, Myounggho	Hanyang Univ.
Jeon, Jongik	Hyundai Motor Company
Choi, Changeun	Hyundai Motor Group

14:40-15:00	SaB1.3
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Control Strategy of Mode Transition between Low-Temperature Combustion and Conventional Combustion in a Light-Duty Diesel Engine, pp. 723-729.

Kim, Kihyun	KAIST
Han, Sangwook	KAIST
Bae, Choongsik	KAIST

15:00-15:20	SaB1.4
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SaB2	Room 402
ACC and Platoon (Regular Session)	
Chair: Tsugawa, Sadayuki	Meijo Univ.
14:00-14:20	SaB2.1
<i>Satellite and Map-Based Long Range Cooperative Adaptive Cruise Control System for Road Vehicles</i> , pp. 732-737.	
Alrifae, Bassam	RWTH Aachen Univ.
Reiter, Matthias	RWTH Aachen
Maschuw, Jan Philipp	RWTH Aachen Univ.
Christen, Frederic	Forschungsgesellschaft Krafftahwesen mbH Aachen
Eckstein, Lutz	RWTH Aachen Univ.
Abel, Dirk	RWTH-Aachen Univ.
14:20-14:40	SaB2.2
<i>When Is It Fuel Efficient for a Heavy Duty Vehicle to Catch up with a Platoon?</i> , pp. 738-743.	
Liang, Kuo-Yun	Royal Inst. of Tech. (KTH)
Mårtensson, Jonas	KTH
Johansson, Karl H.	Royal Inst. of Tech.
14:40-15:00	SaB2.3
<i>Modified Intelligent Driver Model for Driver Safety and Traffic Stability Improvement</i> , pp. 744-749.	
Derbel, Oussama	Univ. de haute alsace
Tamas, Peter	Budapest Univ. of Tech. and Ec.
Zebiri, Hossni	Univ. Haute Alsace UHA Mulhouse
Mourllion, Benjamin	UHA
Basset, Michel	Univ. de Haute-Alsace
15:00-15:20	SaB2.4
<i>A Distributed Model Predictive Control Approach to Active Steering Control of String Stable Cooperative Vehicle Platoon</i> , pp. 750-755.	
Kianfar, Roozbeh	Chalmers Univ. of Tech.
Falcone, Paolo	Chalmers Univ. of Tech.
Fredriksson, Jonas	Chalmers Univ. of Tech.
SaB3	Room 403
Lateral Assistance (Regular Session)	
Chair: Raksincharoensak, Pongsathorn	Tokyo Univ. of Agriculture and Tech.
14:00-14:20	SaB3.1
<i>Mild Merging Path Generation Method with Optimal Merging Point Based on MPC</i> , pp. 756-761.	
Cao, Wenjing	Kyushu Univ.
Mukai, Masakazu	Kyushu Univ.
Kawabe, Taketoshi	Kyushu Univ.
Nishira, Hikaru	Nissan Motor Co., Ltd.
Fujiki, Noriaki	NISSAN MOTOR CO., LTD.
14:20-14:40	SaB3.2
<i>Design of a Strategy for Lane Change Assistance System</i> , pp. 762-767.	
Lee, Junyung	Seoul National Univ.
Kim, Kyuwon	School of Mechanical and Aerospace Engineering, Seoul National U
Kim, Dongwook	Seoul national Univ.
Yi, Kyongsu	Seoul National Univ.
14:40-15:00	SaB3.3
<i>Identification of Yaw Moment of Inertia of a Truck During Travelling</i> , pp. 768-772.	
Lee, Seungyong	The Univ. of Tokyo
15:00-15:20	SaB3.4
<i>Leader-Following Formation Navigation with Virtual Trajectories for Dynamic Multi-Agents</i> , pp. 773-779.	
Kobayashi, Ryo	the Univ. of Electro-Communications
Suzuki, Manabu	the Univ. of Electro-Communications
Nakano, Kazushi	the Univ. of Electro-Communications

SaB4	Room 409
Benchmark Problems (Invited Session)	
Chair: Komori, Satoshi	Mazda Motor Corp.
14:00-14:20	SaB4.1
<i>Identification with Physical and Error Models for Internal Combustion Engine (I)</i> , pp. 780-785.	
Kawaguchi, Masahiro	Tokyo Inst. of Tech.
Yamakita, Masaki	Tokyo Inst. of Tech.
14:20-14:40	SaB4.2
<i>Identification of a Data-Driven Dynamic Model from Virtual Test Bench Results: An Extended Hammerstein Approach (I)</i> , pp. 786-788.	
Schmiechen, Philipp	IAV GmbH
Baumann, Wolf	IAV GmbH
Konstanz, Robert	IAV GmbH
14:40-15:00	SaB4.3
<i>Model Free Tuning of Variable State of Charge Target of Hybrid Electric Vehicles (I)</i> , pp. 789-793.	
Ahmad, Mohd Ashraf	Kyoto Univ.
Baba, Ichiro	Kyoto Univ.
Azuma, Shun-ichi	Kyoto Univ.
Sugie, Toshiharu	Kyoto Univ.
15:00-15:20	SaB4.4
<i>Model Predictive Sliding Mode Control for Four Wheel Steering and Driving Vehicles (I)</i> , pp. 794-799.	
Nonaka, Kenichiro	Tokyo City Univ.
Oda, Takatsugu	Tokyo City Univ.
15:20-15:40	SaB4.5
<i>Development of Energy Management of Hybrid Electric Vehicle for Improving Fuel Consumption Via Sequential Approximate Optimization (I)</i> , pp. 800-805.	
Hagura, Ryuhei	Kanazawa Univ.
Kitayama, Satoshi	Kanazawa Univ.
Yasui, Yuji	Honda R&D Co., Ltd. Japan
SaC1	Room 401
Energy Management Control for XEV IV (Regular Session)	
Chair: Yasui, Yuji	Honda R&D Co., Ltd. Japan
15:50-16:10	SaC1.1
<i>Toward the Development of a Through-The-Road Solar Hybridized Vehicle</i> , pp. 806-811.	
Arsie, Ivan	Univ. of Salerno
D'Agostino, Mario	Univ. of Salerno
Naddeo, Massimo	Univ. of Salerno
Rizzo, Gianfranco	Univ. of Salerno
Sorrentino, Marco	Univ. of Salerno
16:10-16:30	SaC1.2
<i>Electric Mobility: From Fossil Fuels to Renewable Energy, Opportunities and Challenges</i> , pp. 812-817.	
Marano, Vincenzo	Ohio State Univ.
Muratori, Matteo	The Ohio State Univ.
Rizzo, Gianfranco	Univ. of Salerno
Rizzoni, Giorgio	Ohio State Univ.
16:30-16:50	SaC1.3
<i>Optimal Transient Control and Effects of a Small Energy Storage for a Diesel-Electric Powertrain</i> , pp. 818-823.	
Sivertsson, Martin	Linköping Univ.
Eriksson, Lars	Linköping Univ.
SaC3	Room 403
Handling and Stability (Regular Session)	
Chair: Ivanov, Valentin	Ilmenau Univ. of Tech.
15:50-16:10	SaC3.1
<i>Optimal Control for Steady State Drifting of RWD Vehicle</i> , pp. 824-830.	
Chaichaowarat, Ronnapree	Chulalongkorn Univ.

16:10-16:30

SaC3.2

Safe Driving Envelopes for Shared Control of Ground Vehicles, pp. 831-836.

Erlie, Stephen

Stanford Univ.

Fujita, Susumu

NISSAN MOTOR CO., LTD

Gerdes, J. Christian

Stanford Univ.

16:30-16:50

SaC3.3

Maneuverability Analysis of Front Drive Type Personal Vehicle STAVi Using Modeling Error Compensation System, pp. 837-842.

Maruno, Yutaro

Kumamoto Univ.

Dan, Yusuke

Kumamoto Univ.

Zengin, Aydin Tarik

Kumamoto Univ.

Okajima, Hiroshi

Kumamoto Univ.

Matsunaga, Nobutomo

Kumamoto Univ.