2015 International Automatic Control Conference (CACS 2015)

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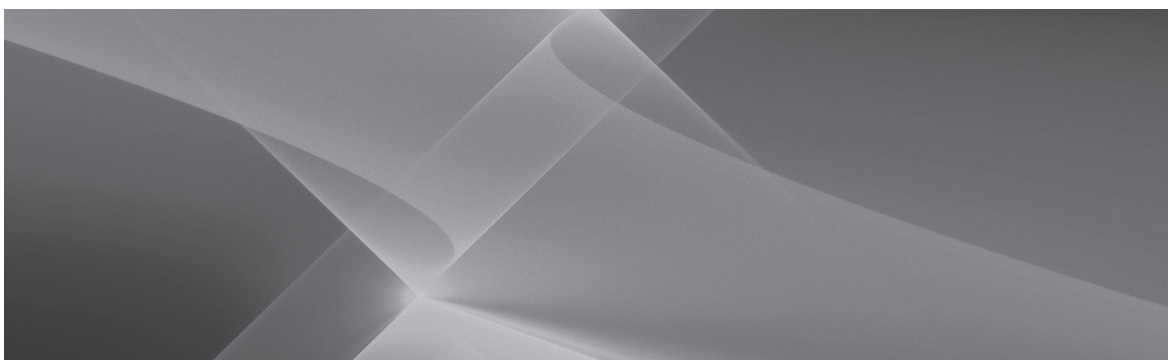
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#1009	Terrain based Localization for Ground Vehicle	Juhui Gim, Changsun Ahn	N/A
#1060	Coverage Control with Density Function in Human-Swarm System	Wei-Tao Li and Yen-Chen Liu	N/A
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#1099	Intelligent Cooperative Formation Control with Collision and Obstacle Avoidance Using RFWCMAC for Uncertain Multi-ballbot Systems	Ching-Chih Tsai, Feng-Chun Tai, Chang Hsuan Chiang	N/A
#1116	Multi-agents Cooperation System Based on a Layered Cooperation Model	Kao-Shing Hwang, Senior Member, IEEE, Hsin-Jung Hsu, and Wei-Cheng Jiang	N/A
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#1129	Two-Scan Labeling Algorithm of Connected Component using Efficient Block-Based Strategy	Wan-Yu Chang, Student Member, IEEE, Yun-Jiun Liu, Student Member, IEEE, Sheng-Yi Chiu, Student Member, IEEE, and Chung-Cheng Chiu, Member, IEEE	N/A
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#1053	Development of a Wireless Sensor Network Monitoring Platform for Positioning Systems	Der-Cherng Liaw, Sung-Ming Lo and Chih-Hsiang Tsai	N/A
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#1115	Mechanical Design and Implementation of a Lower-limb Exoskeleton Rehabilitation System	Chen-Yun Kuo, Kung-Fong Lin, Kai-An Yu, Chung-Wei Su, Chung-Hsien Kuo	N/A

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16:00~16:30	Speech: **Consequential Robotics** **Dr. Sebastian Conran** Director, Marker Block Ltd, United Kingdom
16:30~16:50	Speech: **Shayang Ye's Vision of Robots and Life** Mr. F. C. Tsai President Shayang Ye Industrial Co. Ltd, Taiwan
16:50~17:10	Tea Break & Robot Demo
17:10~17:30	Speech: **Smart home mobile platform–IOT+ big data driving force** Mr. Charles Wu Vice President Matsutek Enterprises Co.,Ltd., Taiwan
17:30~17:50	Speech: **EtherCAT-based Impedance Control and Force Compliance Teaching of a 6-DOF Industrial Robotic Manipulator for Industry 4.0** Prof. Ching-Chih Tsai National Chung-Hsing University, Taichung Taiwan.
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Remark: The content may be modified by the organizing committee.

附註：大會保留更動議程內容的彈性

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#1149i	Intelligent Computation on Symbolic Data Analysis: the Proposed Clustering Technologies for the Real Symbolic Data	Jin-Tsong Jeng, Chen-Chia Chuang, Sheng-Chieh Chang and Nai-Cheng Shih	N/A
#1154i	A Weighted Feature Selection Algorithm for Interval-Value Data	Chih-Ching Hsiao	N/A
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#1127	Brain Wave Controlled Exercise Rehabilitation System with Biosignals Feedback: Circuit System Design	Kuo-Kai Shyu, Po-Lei Lee, Chung-Ying Ho, Tai-Yen Cho, Yu-Wei Liu	N/A
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#1033	Implementation of Emergency Vehicle Preemption Control Systems Using VHDL	Yi-Sheng Huang, Yi-Shun Weng, Weimin Wu and Jiliang Luo	N/A
#1102	Design of One Computationally Improved Deadlock Prevention Based on MFFP Technology in Flexible Manufacturing System	Yen-Liang Pan, Member, IEEE, Ching-Yun Tseng, and Yi-Sheng Huang, Senior Member, IEEE	54

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#1089	Adaptive trajectory tracking control with finite-time stability for robot manipulators	Juro Fujishiro, Yoshiro Fukui and Takahiro Wada	60
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#1073	Optimal Robot Path Planning System by Using a Neural Network-Based Approach	Yi-Wen Chen and Wei-Yu Chiu	85
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Room: RM 301 Time: 10:50-12:05 Nov. 20, 2015	Session Chair: Prof. Chung-Hsien Kuo	**FRB01**

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#1003	IMC-PID Controller Design for Turbine Control Loop Based on Closed-loop Identification	Xiao-Feng Li, Ya-Gang Wang, Member, IEEE	N/A
#1004	Optimal Parameters for Generalized Predictive Control of Vibration Suppression with Stability Constraints	Jiann-Shiun Lew	N/A
#1006	The interval-parametric synthesis of a linear controller of control system with ensured robust degree of stability	Gayvoronskiy Sergey An., Ezangina Tatiana and Khozhaev Ivan	N/A
#1056	Structured Longitudinal Control for Automated Vehicles String	Saïd Mammar, Senior Member IEEE	N/A
#1083	Can we use Beremiz real-time engine for Robot Programmable Logic Controller?	S. Chu, E. Shin, S. Lee, K. Lee, K. Nam	114

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#1052	Position Control of Four-wheeled Mobile Vehicle via Locally Semiconcave Control Lyapunov Function	Kohei Kawamura and Hisakazu Nakamura	119
#1061	Multivariable Controller Tuning Based on Closed-Loop Interaction Using Frequency Responses	Shogo Shinoda, Kazuhiro Yubai, Daisuke Yashiro and Junji Hirai	125
#1064	Sequential Model Predictive Control for Leg/Wheel Mobile Robot using Single Leg Model	Yuki Hagimori, Kenichiro Nonaka-IEEE Member and Kazuma Sekiguchi-IEEE Member	N/A
#1086	End-effector Position Feedback Torque Control of Robot Manipulator via Minimum Projection Method	Hikaru Shibuya, Yu Koyama and Hisakazu Nakamura	N/A
#1029	End-effector Orientation Control of Robot Manipulators via Finite-Time P-PI Control	Toshiaki Muraki, Naoki Sugito, Yasuyuki Satoh and Hisakazu Nakamura	131
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