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**3D Image Processing, Measurement
(3DIPM), and Applications 2016**

**San Francisco, California, USA
14-18 February 2016**

Editors:

William Puech

Robert Sitnik

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Society for Imaging Science & Technology
7003 Kilworth Lane
Springfield, Virginia 22151
USA

Phone: 703-642-9090
Fax: 703-642-9094

info@imaging.org

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3D Image Processing, Measurement (3DIPM), and Applications 2016

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3D Image Processing, Measurement (3DIPM), and Applications 2016

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Wednesday, February 17, 2016

3DIPM/SD&A: Stereoscopic Image Processing and Depth Mapping

Joint Session

Session Chairs: William Puech, University of Montpellier (France) and Michael Weissman, TrueVision Systems (USA)

10:50 am – 12:30 pm

Continental Ballroom 5

This session is jointly sponsored by: Stereoscopic Displays and Applications XXVII and 3D Image Processing, Measurement (3DIPM), and Applications 2016.

10:50 SDA-034

Geometrically constrained sub-pixel disparity estimation from stereo images of the retinal fundus, Mohamad Kharboutly, Carlos Vazquez, Stéphane Coulombe, and Jacques De Guise, École de technologie supérieure (Canada) N/A

11:10 3DIPM-035

3D autostereoscopic display image generation using direct light field rendering, Young Ju Jeong, Yang Ho Cho, Hyoseok Hwang, Hyun Sung Chang, Dongkyung Nam, and C.-C. Jay Kuo, Samsung Advanced Institute of Technology (South Korea) 1

11:30 SDA-036

A new hole filling method based on 3D geometric transformation for synthesized image, Hak Gu Kim and Yong Man Ro, Korea Advanced Institute of Science and Technology (South Korea) N/A

11:50 3DIPM-037

Blue noise sampling of surfaces from stereoscopic images, Frederic Payan, Jean-Luc Peyrot, and Marc Antonini, Laboratory I3S, University Nice - Sophia Antipolis and CNRS (France) - UMR 7271 (France) 7

12:30 – 2:00 pm Lunch Break

EI 2016 Wednesday Plenary and Symposium Awards

Session Chair: Choon-Woo Kim (Inha University)

2:00 – 3:00 PM

Continental Ballroom 5

Intel® RealSense Technology: Adding human-like sensing and interactions to computing devices, Achin Bhowmik, Intel Corporation (USA) N/A

3:00 – 3:30 pm Coffee Break

3D Data Processing and Compression

Session Chair: Robert Sitnik, Warsaw University of Technology (Poland)

3:30 – 5:10 pm

Union Square 25

3:30 3DIPM-396

Secure high capacity data hiding for 3D meshes, Vincent Ltier^{1,3}, Adrian Bors², William Puech¹, and Jean-Pierre Pedeboy³; ¹LIRMM (France), ²University of York (United Kingdom), and ³STRATEGIES (France) 15

3D Image Processing, Measurement (3DIPM), and Applications 2016

3:50 3DIPM-397
Point cloud compression using depth maps, Arnaud Bletterer¹, Frédéric Payan¹, Marc Antonini¹, and Anis Mefteh²; ¹Laboratory I3S, University of Nice - Sophia Antipolis and CNRS (France) - UMR 7271 and ²Cintoo3D (France) 22

4:10 3DIPM-398
Truncated signed distance function volume integration based on voxel-level optimization for 3D reconstruction, Fei Li, Yunfan Du, and Rujie Liu, Fujitsu Research & Development Center Co., Ltd. (China) 28

4:30 3DIPM-399
Depth assisted composition of synthetic and real 3D scenes, Santiago Cortes, Olli Suominen, and Atanas Gotchev, Tampere University of Technology (Finland) 34

4:50 3DIPM-400
Parallax scan based image segmentation using lens supplied metadata, Christopher Mayhew, Ji Gou, and Sanjay Oak, Vision III Imaging, Inc. (USA) N/A

3D Image Processing, Measurement (3DIPM), and Applications 2016 Interactive Papers Session

5:30 – 7:00 pm
 Continental Ballroom 6

The following works will be presented at the EI 2016 Symposium Interactive Papers Session.

3DIPM-401
Efficient filling of disparity holes using resolution decoupling, Alexey Supikov, Maha El Choubassi, and Oscar Nestares, Intel Corporation (USA) 43

3DIPM-402
Temporal domain stereo matching based on feature points for restriction of error propagation, Ji-Hun Mun and Yo-Sung Ho, GIST (South Korea) 50

3DIPM-403
Cavern halos: Exploring spatial and nonspatial cosmological data in an immersive virtual environment, Carlos Uribe; University of Illinois at Chicago and EVL (USA) N/A

3DIPM-404
Non-uniform resampling in perspective compensated large scale 3D visualization, Maria Shcherban, Olli Suominen, and Atanas Gotchev, Tampere University of Technology (Finland) 57

3DIPM-405
Depth estimation algorithm for color coded aperture camera, Ivan Panchenko, Vladimir Paramonov, and Victor Bucha, Samsung R&D Institute Russia (Russian Federation) 64

EI 2016 Symposium Interactive Papers Session
5:30 – 7:00 PM
 Continental Ballroom 6

Thursday February 18, 2016

3D Acquisition and Preprocessing

Session Chair: Robert Sitnik, Warsaw University of Technology (Poland)

9:10 – 10:10 am
 Golden Gate 6/7

9:10 3DIPM-406
High-fidelity Time-of-Flight edge sampling using superpixels, Thomas Hach¹, Sascha Knab², and Johannes Steuer¹; ¹Arnold & Richter Cine Technik and ²Hochschule RheinMain (Germany) 70

9:30 3DIPM-407
3D shape template generation from RGB-D images capturing a moving and deforming object, Hikari Takehara, Yuta Nakashima, Tomokazu Sato, and Naokazu Yokoya, Nara Institute of Science and Technology (Japan) 79

9:50 3DIPM-408
Implementation of 3D object reconstruction using multiple Kinect cameras, Dong-won Shin and Yo-Sung Ho, Gwangju Institute of Science and Technology (South Korea) 86

10:10 – 10:40 am Coffee Break

3DIPM/IPAS: 3D Scene Sensing and Object Recording Joint Session

Session Chair: Robert Sitnik, Warsaw University of Technology (Poland)

10:40 am – 12:10 pm
 Golden Gate 6/7

This session is jointly sponsored by: 3D Image Processing, Measurement (3DIPM), and Applications 2016, and Image Processing: Algorithms and Systems XIV.

10:40
 Joint Session Introduction

10:50 3DIPM-044
Shadow detection on 3D point cloud, Shuyang Sheng and B. Keith Jenkins, University of Southern California (USA) 93

11:10 3DIPM-045
Im2Fit: Fast 3D model fitting and anthropometrics using single consumer depth camera and synthetic data, Qiaosong Wang¹, Vignesh Jagadeesh², Bryan Ressler³, and Robinson Piramuthu³; ¹University of Delaware and ²eBay Research Labs (USA) 98

11:30 3DIPM-046
Human detection from still depth images, Gulsum Can and Helin Dutagaci, Eskisehir Osmangazi University (Turkey) 105

11:50 IPAS-047
Tracking the guitarist's fingers as well as recognizing pressed chords from a video sequence, Zhao Wang and Jun Ohya, Waseda University (Japan) N/A

12:10 – 2:00 pm Lunch Break

3D Image Processing, Measurement (3DIPM), and Applications 2016

3DIPM/IMSE: Image Sensors and Systems for 3D Imaging Joint Session

Session Chair: William Puech, University of Montpellier (France)

1:50 – 3:20 pm

Golden Gate 6/7

This session is jointly sponsored by: Image Sensors and Imaging Systems 2016, and 3D Image Processing, Measurement (3DIPM), and Applications 2016.

1:50**Joint conference introduction**

2:00

IMSE-048

A time-of-flight CMOS range image sensor using 4-tap output pixels with lateral-electric-field control, Taichi Kasugai¹, Sang-Man Han¹, Hanh Trang¹, Taishi Takasawa¹, Satoshi Aoyama², Keita Yasutomi¹, Keiichiro Kagawa¹, and Shoji Kawahito¹; ¹Shizuoka University and ²Brookman Technology (Japan) N/A

2:20

IMSE-049

Design, implementation and evaluation of a TOF range image sensor using multi-tap lock-in pixels with cascaded charge draining and modulating gates, Trang Nguyen¹, Taichi Kasugai¹, Keigo Isobe², Sang-Man Han¹, Taishi Takasawa¹, De Xing Liao¹, Keita Yasutomi¹, Keiichiro Kagawa¹, and Shoji Kawahito¹; ¹Shizuoka University and ²Brookman Technology (Japan) N/A

2:40

3DIPM-050

Markerless motion capture with multi-view structured light, Ricardo Garcia and Avidah Zakhor, University of California, Berkeley (USA)

114

3:00

3DIPM-051

Towards automated, high resolution 3D scanning of large surfaces for cultural heritage documentation, Robert Sitnik¹, Eryk Bunsch², Grzegorz Maczkowski¹, Wojciech Zaluski¹, Krzysztof Lech¹, Jakub Michonki¹, , Jakub Krzeslowski¹, and Piotr Forys¹, Warsaw University of Technology and ²Museum of King Jan III's Palace at Wilanów (Poland) 121

3:20 – 3:50 pm Coffee Break

3D Industrial Applications

Session Chair: William Puech, University of Montpellier (France)

3:50 – 5:00 pm

Golden Gate 6/7

3:50

3DIPM-409

Mobile version of Digital Image Correlation for deformation measurements of engineering objects, Marcin Malesa, Dariusz Naploszek, Krzysztof Kuczynski, and Pawel Skrzypczak, Warsaw University of Technology (Poland) 128

4:10

3DIPM-410

Structural internal deterioration detection with motion vector field image analysis using monocular camera, Hiroshi Imai, Masahiko Ohta, and Kazuhito Murata, NEC Corporation (Japan) 134

4:50**Closing Remarks**