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	Mapping grasping motion of the hand between Master and Slave in a low-dimensional latent space Chuanyu GUO, Yang LIU, Ayaka Matsuzaka, Takuya SHIRATO, Tetsuya MOURI, Akio Namiki	1941
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	A VR Training System with Haptic Force Feedback for the Robotic Endovascular Surgery Yu Song, Shuxiang Guo, Linshuai Zhang	1964

	CombX: Design of a Haptic Device for Teleoperation Bin Zhao, Shu'an Zhang, Zhonghao Wu, Qi Li, Kai Xu	1969
	Estimation of Hand Position and Posture using Inertial Sensors and its Application to Robot Teaching System Akihito Ito, Nobutaka Tsujiuchi, Kenji Horio, Keisuke Kitano	1975
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	Validation of a small flying e-nose system for air pollutants control: A plume detection case study from an agricultural machine João Valente, Sandra Munniks, Imke de Man, Lammert Kooistra	1993
	A Survey on the Application Trends of Home Service Robotics Georgios A. Zachiotis, George Andrikopoulos, Randy Gomez, Keisuke Nakamura, George Nikolakopoulos	1999
	Design and Analysis of Continuous Rotating Multifunctional Mechanical Gripper Menghui Pei, Kun Xu, Xilun Ding, Shuiqing Jiang, Xiangyu Gao	2007
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