

# **2019 International Conference on Mechatronics, Robotics and Systems Engineering (MoRSE 2019)**

**Bali, Indonesia**  
**4 – 6 December 2019**



**IEEE Catalog Number:** CFP19MOR-POD  
**ISBN:** 978-1-7281-3985-2

**Copyright © 2019 by the Institute of Electrical and Electronics Engineers, Inc.  
All Rights Reserved**

*Copyright and Reprint Permissions:* Abstracting is permitted with credit to the source. Libraries are permitted to photocopy beyond the limit of U.S. copyright law for private use of patrons those articles in this volume that carry a code at the bottom of the first page, provided the per-copy fee indicated in the code is paid through Copyright Clearance Center, 222 Rosewood Drive, Danvers, MA 01923.

For other copying, reprint or republication permission, write to IEEE Copyrights Manager, IEEE Service Center, 445 Hoes Lane, Piscataway, NJ 08854. All rights reserved.

***\*\*\* This is a print representation of what appears in the IEEE Digital Library. Some format issues inherent in the e-media version may also appear in this print version.***

IEEE Catalog Number:	CFP19MOR-POD
ISBN (Print-On-Demand):	978-1-7281-3985-2
ISBN (Online):	978-1-7281-3984-5

**Additional Copies of This Publication Are Available From:**

Curran Associates, Inc  
57 Morehouse Lane  
Red Hook, NY 12571 USA  
Phone: (845) 758-0400  
Fax: (845) 758-2633  
E-mail: [curran@proceedings.com](mailto:curran@proceedings.com)  
Web: [www.proceedings.com](http://www.proceedings.com)

## TABLE OF CONTENT

	Page
<b>Welcome Message.....</b>	iii
<b>Conference Organization.....</b>	iv
<b>Technical Program Committee and Reviewers.....</b>	vi
<b>Technical Sessions .....</b>	viii
<b>Table of Content.....</b>	xvii
<b>Designing a Testbed to Assess Secure Control of Cyber-Physical Systems</b>	<b>1</b>
<i>Park, E.; Chan, K.C.</i>	
<b>Modeling and Simulation of a Multi-Robot System Architecture</b>	<b>8</b>
<i>Sadik, A. R.; Goerick, C.; Muehlig, M.</i>	
<b>Brain Tumor Classification with Fisher Vector and Linear Classifier for T1-weighted Contrast-enhanced MRI Images</b>	<b>15</b>
<i>Mubarok, A. F. A.; Thias, A. H.; Handayani, A.; Danudirdjo, D.; Rajab, T. E.</i>	
<b>Development of On-Demand Controller for Continuous Positive Airways Pressure</b>	<b>20</b>
<i>Amrulloh, Y. A.; Hisif, B. A.; Wati, D. A. R.</i>	
<b>Power Coefficient Analysis of Savionus Wind Turbine Using CFD Analysis</b>	<b>24</b>
<i>Trisakti, M; Halim, L.; Arthaya, B. M.</i>	
<b>Parking Space Optimization Using Simplex Method Linear Programming</b>	<b>30</b>
<i>Crisostomo, C. I. C.; Baldovino, R. G.</i>	
<b>Comparison of Neural Biomarker Assessment Methods for Early Detection of Alzheimer's Disease</b>	<b>34</b>
<i>Yang, D.; Hong, K.-S.</i>	
<b>Devising A New Portable Electronic Firing System</b>	<b>40</b>
<i>Ali, M.; Wijayanto, T.</i>	
<b>A Millimeter-Wave Phased Array for Communication and Sensing Systems</b>	<b>45</b>
<i>Huynh, C.; Lee, J.; Bae, J.; Lee, D.; Hsiao, M. J.; Nguyen, C.</i>	
<b>Mamdani based Fuzzy Logic Controller for A Wheeled Mobile Robot with Obstacle Avoidance Capability</b>	<b>49</b>
<i>Najmurorokman, A.; Kusnandar; Komarudin, U.; Sunubroto; Sadiyoko, A.; Iskanto, T. Y.</i>	

<b>Mapping and Navigation with Four-wheeled Omnidirectional Mobile Robot Based on Robot Operating System</b>	<b>54</b>
<i>Quang, H.Q.; Manh, T. N.; Manh, C. N.; Tien, D. P.; Van, M. T.; Kim, D. H. T.; Thanh, V. N. T.; Duan, D. H.</i>	
<b>Robust Control of Infinite-dimensional Mechatronic Systems</b>	<b>60</b>
<i>Iftar, A.</i>	
<b>Preliminary Design of Seed Spreading Robot as an Educational Mechatronic Project</b>	<b>64</b>
<i>Arthaya, B. M.; Naa, C. F.; Roinaldo</i>	
<b>Closed Loop System Identification of a DC Motor using Fractional Order Model</b>	<b>69</b>
<i>Shah, P.; Sekhar, R.</i>	
<b>Efficient Pavement Crack Area Classification Using Gaussian Mixture Model Based Features</b>	<b>75</b>
<i>Ogawa, S.; Matsushima, K.; Takahashi, O.</i>	
<b>Analysis of Power, Temperature, and Performance on Mobile Application Processor</b>	<b>81</b>
<i>Lee, D. H., Hyun Hak Cho, H. H.; Jeong, O. H.</i>	
<b>Experimental Implementation of Fixed-Time Leader-Follower Axial Alignment Tracking</b>	<b>86</b>
<i>Anggraeni, P.; Candra, W. A.; Defoort, M.; Djemai, M.</i>	
<b>Security System ATM Machine with One-Time Passcode on M-Banking Application</b>	<b>92</b>
<i>Munadi, R.; Irawan, A. I.; Romiadi; Y. F.</i>	
<b>ARX/ARMAX Modeling and Fractional Order Control of Surface Roughness in Turning Nano-Composites</b>	<b>97</b>
<i>Sekhar, R.; Singh, T. P.; Pritesh Shah, P.</i>	
<b>Cybersickness Evaluation While Using Driving Simulator in a Head-Mounted Display Environment</b>	<b>103</b>
<i>Suwarno, D. C. D.; Wijayanto, T.; Trapsilawati, F.</i>	
<b>Crack Detection Using Spectral Clustering: Self-Tuning Considering Crack Feature and Connections</b>	<b>107</b>
<i>Shiotsuka, D.; Matsushima, K.; Takahashi, O.</i>	
<b>Comparative Study for PV Power Stabilization Technology Using Matlab Simulink</b>	<b>112</b>
<i>Garniwa, I.; Kuncoro, M.; Darussalam, R.</i>	
<b>VR Based Visualization of Robotic Workcells Using Cryengine</b>	<b>118</b>
<i>Karaoglu, E. O.; Tükel, D.; Arthaya, B. M.</i>	
<b>Design of Propeller Turbine for Micro-Hydro-Electric Power Plant at Cikapundung River - Bandung</b>	<b>122</b>

<i>Sudiro, R. D.; Arthaya, B. M., Halim, L.</i>	
<b>Power Electronics in the Engineering Field: A Perception Comparison Between Undergraduate and Graduate Students Using Fuzzy Logic Type 2 Signal Detection Theory</b>	128
<i>Reyes, G. E. B.; Ponce, P.; Ayyanar, R.</i>	
<b>DenseNet with Spatial Pyramid Pooling for Industrial Oil Palm Plantation Detection</b>	134
<i>Abdani, S. R.; Zulkifley, M. A.</i>	
<b>Modeling of Tumor Growth: An Incremental Development Framework</b>	139
<i>Iftekhar, L.; Islam, T.; Kamal, M. S.; Amir, S.</i>	
<b>Development of Virtual Firefighting Robots Using Breitenberg and Fuzzy Logic Methods</b>	145
<i>Putra, M. D.; Nazaruddin, Y. Y.</i>	
<b>Gain-Scheduled Control for Active Suspension Using Estimated Uncertain Parameters</b>	151
<i>Matsuura, T.; Matsushita, M.; Chen, G.; Takami, I.</i>	
<b>Integration of Blockchains with Management Information Systems</b>	157
<i>Chan, K. C.; Zhou, X.; Gururajan, R.; Zhou, X.; Ally, M.; Gardiner, M.</i>	
<b>Game-Theoretic and Genetic-based Approach for Cooperative Mission-oriented Swarms of Drones</b>	163
<i>Saputro, N.</i>	
<b>Simulation of a Sliding Mode Controller for a Uniaxial Seismic Shake Table</b>	169
<i>Crisostomo, C. I. C.; Malalis, R. V. C.; Saysay, R. S.; Baldovino, R. G.</i>	
<b>Adaptive Control for Jib Crane System with Rope Hoisting and Uncertain Parameters</b>	174
<i>Ishikura, S.; Chen, G.; Takami, I.</i>	
<b>Initial Concept for Increasing Polycrystalline Fixed Solar Panel Efficiency with Water Treatments</b>	180
<i>Taruna, C.; Halim, L.; Arthaya, B. M.</i>	
<b>Attitude Control of Satellites Actuated by Hybrid Actuators</b>	186
<i>Giri, D. K.</i>	
<b>Adaptive Dynamic Surface Control for Car Driving Simulator Based on Artificial Neural Network</b>	192
<i>Tien, K. N.; Kim, D. H. T.; Manh, T. N.; Manh, C. N.; Bach, N. P. V.; Quang, H. D.</i>	
<b>Miniaturization of Circular Resonators Waveguide at SHF Frequency Using Floral Foam Electromagnetic Engineering</b>	198
<i>Andhita, F. R.; Yusuf, R. A. M.; Maulana, M. H.; Ludiyati, H.</i>	

<b>Performance of SC-FDMA for LTE Uplink Under Different Modulation Schemes</b>	<b>202</b>
<i>Roy, J. S.; Mishra, S. S.</i>	
<b>Collector: A Vision-Based Semi-Autonomous Robot for Mangrove Forest Exploration and Research</b>	<b>207</b>
<i>Shahria, T.; Aimon Rahman, A.; Hasib Zunair, H.; Shoaib Bin Aziz, S. B.</i>	
<b>Arduino Uno-Based Maximum Power Point Tracking for PV Module Using Perturb and Observe Algorithm</b>	<b>213</b>
<i>Batu, A. O.; Soepardjo, H.; Prajitno, P.</i>	
<b>Brain Tumor Semi-automatic Segmentation on MRI T1-weighted Images using Active Contour Models</b>	<b>217</b>
<i>Thias, A. H.; Mubarok, A. F. A.; Handayani, A.; Danudirdjo, D.; Rajab, T. E.</i>	
<b>Bottled Water Identification &amp; Fraud Detection Using Spectroscopy &amp; Convolutional Neural Network</b>	<b>222</b>
<i>Thai, P. Q.; Dat, P. T.</i>	
<b>Automatic Pavement Crack Detection Using Multi-Scale Image and Neighborhoods Information</b>	<b>227</b>
<i>Komori, T.; Matsushima, K.; Takahashi, O.</i>	
<b>Linear Wireless Sensor Networks for Cathodic Protection Monitoring of Pipelines</b>	<b>233</b>
<i>Kara, A.; Imran, M. A. A.; Karadag; K.</i>	
<b>Improving Temperature Sensor Accuracy in The IoT Trainer Kit by Linear Regression Method</b>	<b>237</b>
<i>Hariyanto, T.; Rahayu, M.; Satria, F.; Fadhlhan, M. Y.</i>	
<b>Template-Based Space-Saving Approach for SMS Storage in A Server</b>	<b>241</b>
<i>Newaz, S.; AUddin, A. H.; Islam, A. B. M. A. A.</i>	
<b>Controlling an Exoskeleton with EMG Signal to Assist Load Carrying: A Personalized Calibration</b>	<b>246</b>
<i>Treussart, B.; Geffard, F.; Vignais, N.; Marin, F.</i>	
<b>Design and Kinematics Analysis of Parallel Robotic Arm for Urological Surgery</b>	<b>253</b>
<i>Tan, K.; Shi, H.; Wang, Y.; Yang, L.</i>	
<b>Analysis of RNA-Seq Data of 10000 Samples of Single-cell Transcriptome</b>	<b>259</b>
<i>Afroze, T; Rahman, A.; Sarkar, M.; Sadique, A.; Alam, J.; Rahman, S.; Hossain, M.</i>	
<b>Energy-Based Modeling and Swing Up Control Synthesis of an Inverted Pendulum System</b>	<b>265</b>
<i>Chandra, J.; Tamba, T. A.; Sadiyoko, A.</i>	
<b>Generic Linear ESO for the State Observation of Unknown Nonlinear SISO Systems</b>	<b>270</b>
<i>Amokrane, F.; Piat, E.; Abadie, J.; Drouot, A.; Escareno, J.</i>	