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Prof. Dr. Alin Albu-Schäffer "Service Robotics: From Space to Industrial Manufacturing and Healthcare"

Room 1

Chair: Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)

Wednesday, December 9 10:50 - 11:10

Coffee Break & Networking

Room: General

Poster Session

Room 3

10:50 Quasi-static loaded circular testing of serial articulated industrial manipulators

Monica Gonzalez, Arian Hosseini, Nikolas Alexander Theissen and Andreas Archenti (KTH Royal Institute of Technology, Sweden)...1

Wednesday, December 9 11:45 - 12:45

Lunch Break

Room: General

Wednesday, December 9 12:45 - 13:45

Industrial Robots

Room 1

Chair: Alexander Meißner (Dürr Systems GmbH, Bietigheim-Bissingen, Germany)

12:45 <u>Supervised Autonomous Interaction in Unknown Territories - Concept for Industrial Applications in the</u> near Future

Jonas Christoph Wittmann, Jonis Kiesbye, Daniel Rixen and Ulrich Walter (Technical University of Munich, Germany)...7

13:05 <u>Evaluation of path planning strategies in automated honeycomb potting</u>
Martin Harnisch and Johann Kipping (Hamburg University of Technology, Germany); Thorsten Schüppstuhl (Technische Universität Hamburg-Harburg, Germany)...15

13:25 <u>Operation and experimental evaluation of a 12-axis robot-based setup used for 3D-printing</u>
Zsolt Kállai and Maik Dammann (Hamburg University of Technology, Germany); Thorsten Schüppstuhl (Technische Universität Hamburg-Harburg, Germany)...

Mobile Robotics

Room 2

Chair: Birgit Graf (Fraunhofer IPA, Germany)

12:45 <u>Traveling Drinksman</u>

Michele Persiani (Umeå University, Sweden); Cagatay Odabasi and Florenz Graf (Fraunhofer IPA, Germany); Mohit Kalra (University of Stuttgart & Fraunhofer IPA, Germany); Thomas Hellström (Umeå University, Sweden); Birgit Graf (Fraunhofer IPA, Germany)...31

13:05 <u>Robust and Precise Localization of Mobile Robots using EFIR Estimation for Fusing Odometry with Position Measurements</u>

Daniel Heß (University of Applied Sciences and Arts, Dortmund, Germany); Christof Röhrig (University of Applied Sciences and Arts in Dortmund, Germany)...37

13:25 <u>Dynamic Obstacle Layer: A new concept to avoid moving obstacles in local path planning using ROS</u>
Tonja Heinemann, Moritz Villinger and Armin Lechler (University of Stuttgart, Germany); Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)...44

Business Track

Room 4

Wednesday, December 9 13:45 - 14:25

Carl Doeksen "3M's Automation Journey: Driving Growth & Productivity for our customers"

Room 1

Chair: Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)

Wednesday, December 9 14:25 - 14:45

Coffee Break & Networking

Room: General

Poster Session

Room 3

Robot programming system for human-robot cooperation and collaboration

Julia Berg (Fraunhofer IGCV, Germany); Johannes Schilp (University of Augsburg, Germany)...52 <u>Multi-modal Visual Withdrawal Detection for Inventory Management on a Robotic Care Cart</u>

Jochen Lindermayr and Cagatay Odabasi (Fraunhofer IPA, Germany); Timur Alexander Wohlleber (Universität Stuttgart, Germany); Birgit Graf (Fraunhofer IPA, Germany)...58

Wednesday, December 9 14:45 - 15:45

IERA Session

Room 1

Wednesday, December 9 15:45 - 17:05

Components and Technologies

Room 1

Chair: Ulrike Thomas (Chemnitz University of Technology, Germany)

15:45 A New Compliant Leg for the Humanoid Robot Forrest

Hongxi Zhu and Ulrike Thomas (Chemnitz University of Technology, Germany)...N/A

- 16:05 A New Low Cost Three-Finger Gripper with Hybrid Control for Soft Touch Behaviour Julian Bonse and Ulrike Thomas (Chemnitz University of Technology, Germany)...N/A
- 16:25 <u>Design of Compact Omnidirectional Wheel Modules with Internal Differential Kinematics</u>
 Theo Jacobs and Erik Schäfer (Fraunhofer IPA, Germany)...64
- 16:45 *The multi-segment controller of a flexible arm*

Ryszard Leniowski (Rzeszów University of Technology, Poland); Lucyna Leniowska (University of Rzeszow, Poland)...71

Wednesday, December 9 15:45 - 16:45

Business Track

Room 4

Thursday, December 10

Thursday, December 10 9:00 - 10:20

Control

Room 1

9:00 <u>Automatic Synthesis of a Saturating State Space Controller Based on Convex Optimization for Industrial</u> Robots

Lorenz Halt (Fraunhofer IPA, Germany); Andreas Pott (University of Stuttgart, Germany)...79

9:20 High Fidelity Real-Time Hybrid Substructure Testing Using Iterative Learning Control

Christina Insam, Arian Kist and Daniel Rixen (Technical University of Munich, Germany)...85
9:40 <u>Genetic Approach for Hardware-in-the-loop Optimization in a Multiple Degree-of-Freedom Coupled</u>
Dynamics System

Gustavo Jose Giardini Lahr, Luiz Marão, Henrique B Garcia, Thiago Boaventura and Glauco Caurin (University of São Paulo, Brazil)...92

10:00 Evaluating the Robustness of HJB Optimal Feedback Control

Michael Lutter (Technical University of Darmstadt, Germany); Debora Clever (ABB AG, Corporate Research, Germany); Boris Belousov (Technical University of Darmstadt, Germany); Kim Listmann (ABB Corporate Research Center Germany, Germany); Jan Peters (Technische Universität Darmstadt & Max-Planck Institute for Intelligent Systems, Germany)...99

Future of Work

Room 2

Chair: Alfred Hypki (Ruhr-Universität Bochum, Lehrstuhl für Produktionssysteme (LPS), Germany)

9:00 <u>PowerGrasp - Design and Evaluation of a Modular Soft-Robotic Arm Exosuit for Industrial Applications</u>
Jean-Paul Goppold, Jan Kuschan and Henning Schmidt (Fraunhofer IPK, Germany); Mirko Wolschke and
Jana Liebach (Reha-Zentrum Lübben, Germany); Jörg Krüger (Fraunhofer IPK, Germany); Roman
Hackbart (Würth Electronics, Germany); Jan Kostelnik (Würth Elektronik GmbH, Germany); Gregor
Thiele (Fraunhofer Gesellschaft, Germany)...107

9:20 Dual arm robot control by hands gestures using ROS

Zoltán Forgó (Sapientia University, Romania); Miguel Angel Villanueva Portela (Nation University of Colombia, Colombia); Alfred Hypki and Bernd Kuhlenkötter (Ruhr-Universität Bochum, Lehrstuhl für

Produktionssysteme (LPS), Germany)...115

9:40 <u>Finger Pointer Based Human Machine Interaction for Selected Quality Checks of Industrial Workpieces</u>
Christian Bräuer-Burchardt, Florian Siegmund, Daniel Höhne and Peter Kühmstedt (Fraunhofer Institute for Applied Optics and Precision Engineering IOF, Germany); Gunther Notni (Fraunhofer Institut für Angewandte Optik und Feinwerktechnik, Germany)...121

10:00 A Cooperative HCI Assembly Station with Dynamic Projections

Christian Lengenfelder, Christian Frese, Angelika Zube, Michael Voit and Jürgen Beyerer (Fraunhofer IOSB, Germany)...127

Thursday, December 10 10:20 - 10:40

Coffee Break & Networking

Room: General

Poster Session

Room 3

10:20 <u>Can knowledge-based offline-programming compensate for the lack of welding specialists?</u>
Jobst Bickendorf (Autocam Informationstechnik GmbH, Germany)...135

Thursday, December 10 10:40 - 11:40

Collaborative Robots

Room 1

Chair: Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)

10:40 <u>Towards Collaborative Robots as Intelligent Co-workers in Human-Robot Joint Tasks: what to do and who does it?</u>

Ana Isabel Barros Cunha (University of Minho & Center for Computer Graphics, Portugal); Flora Ferreira (Center of Mathematics, University of Minho, Portugal); Emanuel Sousa (Center for Computer Graphics, University of Minho, Portugal); Luís Louro, Paulo Vicente, Sérgio Monteiro, Wolfram Erlhagen and Estela Bicho (University of Minho, Portugal)...141

11:00 <u>An Architecture for AR-based Human-Machine Interaction with Application to an Autonomous Mobile</u> Robot Platform

Alexander Atanasyan (Institute for Man-Machine Interaction, RWTH Aachen University, Germany); Juergen Rossmann (Technical University of Aachen, Germany)...149

11:20 <u>Development of devices applied to collaborative robot production system based on Collaborative Safety / Safety 2.0</u>

Hidetoshi Fukui (Manufacturer & IDEC Corporation, Japan); Takayoshi Shimizu and Ikuo Maeda (IDEC Corporation, Japan)...155

Robot Programming

Room 2

Chair: Mihai Dragan (University of Stuttgart & ISW, Germany)

10:40 <u>Using Task-Specific Workspace Maps to Plan and Execute Complex Robotic Tasks in a Flexible Multi-Robot Setup</u>

Timo Jens Bachmann (German Aerospace Center (DLR), Germany); Korbinian Nottensteiner (German Aerospace Center (DLR), Institute for Robotics and Mechatronics, Germany); Ismael Rodriguez Brena (Deutsches Zentrum für Luft- und Raumfahrt e. V., Germany); Andreas Stemmer and Maximo Roa (DLR, Germany)...161

11:00 <u>Use CAD Data for Intuitive Definition of Robot Actions in a Skill-based Robot Application Development</u> Environment

Fan Dai (ABB AG & Corporate Research, Germany); Nuo Li (ABB AG, Corporate Research Germany, Germany); Debora Clever (ABB AG, Corporate Research, Germany)...169

11:20 <u>Robot Path Generation for Curve Manufacturing Processes from Unstructured CAD Data: An Off-line Programming Method</u>

Nikolaj W. Leth and Henrik Petersen (University of Southern Denmark, Denmark)...175

Business Track

Room 4

Thursday, December 10 11:40 - 12:20

Prof. Dr. Carme Torras Genís "Assistive Robotics: AI Challenges and Ethics Education based on Science Fiction"

Room 1

Chair: Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)

Thursday, December 10 12:20 - 13:20

Lunch Break

Room: General

Thursday, December 10 13:20 - 13:40

IERA Award Ceremony

Room 1

Thursday, December 10 13:40 - 14:20

Dr. Andrew A. Goldenberg "Bridging Between AI and Robotics for Business and Product Development"

Room 1

Chair: Alexander Verl (Stuttgart University, Institute for Control Engineering of Machine Tools, Germany)

Thursday, December 10 14:20 - 15:20

Simulation and Workspace Planning

Room 1

14:20 <u>Interactive Workspace Layout focusing on the Reconfiguration with Collaborative Robots in Modular Production Systems</u>

Michael Wojtynek (CoR-Lab & University Bielefeld, Germany); Sebastian Wrede (Bielefeld University, Germany)...183

14:40 <u>The Virtual Robotics Lab in education: Hands-on experiments with virtual robotic systems in the Industry</u> 4.0 era

Michael Schluse (Technical University of Aachen, Germany); Marc Priggemeyer (RWTH Aachen University, Germany); Juergen Rossmann (Technical University of Aachen, Germany)...191

15:00 <u>Virtual Commissioning with Mixed-Reality for Next-Generation Robot-Based Mechanical Component Testing</u>

Michael Filipenko, Alwin Hoffmann, Alexander Poeppel, Wolfgang Reif, Andreas Monden and Markus Sause (University of Augsburg, Germany)...199

AI in Robotics - Methods

Room 2

Chair: Karsten Berns (Technische Universität Kaiserslautern, Germany)

14:20 <u>UEM-CNN: Enhanced Stereo Matching for Unstructured Environments with Dataset Filtering and Novel Error Metrics</u>

Nina Felicitas Heide and Samuel Gamer (Fraunhofer IOSB, Germany); Michael Heizmann (Karlsruhe Institute of Technology, Germany)...205

14:40 Model-Free Grasp Learning Framework based on Physical Simulation

Marc A Riedlinger (University of Stuttgart, Germany); Markus Völk, Kilian Kleeberger, Muhammad Usman Khalid and Richard Bormann (Fraunhofer IPA, Germany)...213

15:00 Spatial scene representation and navigation in a mobile robot using RGB-D camera

Marek Jaszuk (University of Information Technology and Management in Rzeszow, Poland); Wojciech Pałka (Academic High School, Poland); Michał Furgał (University of Information Technology and Management in Rzeszow, Poland); Dawid Darłak (Academic High School, Poland); Janusz Starzyk (Ohio University, USA)...221

Business Track

Room 4

Thursday, December 10 15:20 - 15:40

Coffee Break & Networking

Room: General

Poster Session

Room 3

15:20 A Pendulum Apparatus to Evaluate Unconstrained Human-Robot Contact

Harald Staab (ABB AG, Germany); Bjoern Matthias (ABB AG Corporate Research, Germany); Christoph Byner (ABB AG, Germany); Debora Clever (ABB AG, Corporate Research, Germany)...229

15:30 <u>Structure of an Industry 4.0 Compliant Architecture Component for the Development of Simulation-based Control Applications in Cyber-Physical Systems</u>

Marc Priggemeyer (RWTH Aachen University, Germany); Juergen Rossmann (Technical University of Aachen, Germany)...237

Thursday, December 10 15:40 - 16:40

AI in Robotics - Applications

Room 1

15:40 Automated Item Picking for fashion articles using Deep Learning

Moritz Weisenböhler and Christian Wurll (Karlsruhe University of Applied Sciences, Germany)...243

16:00 Robot Learning - An Industrial Perspective on Challenges and Opportunities

Arne Wahrburg (ABB AG Corporate Research, Germany); Thomas Reisinger (ABB Automation GmbH, Germany); Rene Kirsten (ABB AG, Corporate Research, Germany); Kim Listmann (ABB Future Labs Switzerland); Nima Enayati (ABB AG Corporate Research, Germany)...251

16:20 Application of Ontologies for Semantic Scene Segmentation and Object Recognition

Pierre Venet (Magazino GmbH, Germany); Kirill Safronov (KUKA Deutschland GmbH, Germany); Aaronkumar Ehambram and Sven Wagner (Leibniz Universität Hannover, Germany); Jürgen Bock (KUKA Deutschland GmbH, Germany); Uwe Zimmermann (KUKA Roboter GmbH, Germany)...258

Robotics in Production

Room 2

Chair: Rene Kirsten (ABB Automation GmbH, Germany)

15:40 Towards Visual Referencing for Location Based Services in Industrial Settings

Daniel Schoepflin, Michael Brand and Martin Gomse (Hamburg University of Technology, Germany); Thorsten Schüppstuhl (Technische Universität Hamburg-Harburg, Germany)...265

16:00 Methodology for choosing the best suitable strategy of robot trajectory adjustment

Matthias Neuhaus, Sinje Kollan, Jobst Bickendorf and Alina Müller (TU Dortmund, Germany)...273

16:20 <u>Machine learning approaches for offline-programming optimization in robotic painting</u>
Julian Ricardo Diaz Posada (Dürr Systems AG, Germany); Alexander Meißner (Dürr Systems GmbH,
Bietigheim-Bissingen, Germany); Gauthier Hentz and Nikolai D'Agostino (Employee, Germany)...280

Thursday, December 10 15:40 - 16:10

Business Track

Room 4

Thursday, December 10 16:40 - 16:50

Best Paper Award

Room 1

Thursday, December 10 16:50 - 17:00

Outlook for ISR 2021

Room 1