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	The intelligent biped robot AIRO: System overview and omnidirectional walking method design Yun Liu, Anhuan Xie, Shiqiang Zhu, Jason Gu	1911
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	Geometry-appearance Ensemble Object Association for Semantic SLAM Peiqiang Li, Liang Yuan, Teng Ran, Jianbo Zhang	1934
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	A Miniaturized Pneumatic Electrode Gripper for Robotic Cochlear Implant Surgery Hongyan Gao, Yun Zou, Shaoping Huang, Weidong Chen, Anzhu Gao	1958
	Deep Reinforcement Learning-Based Control for Stomach Coverage Scanning of Wireless Capsule Endoscopy Yameng ZHANG, Long Bai, Li Liu, Hongliang Ren, Max Meng	1964
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	Information Map Prediction based on Learning Network for Reinforced Autonomous Exploration Yinchuan Wang, Mingrui Xu, Xiangyu Chen, Xiang Zhang, Chaoqun Wang, Rui Song	1982
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	Skill-based Multi-objective Reinforcement Learning of Industrial Robot Tasks with Planning and Knowledge Integration Matthias Mayr, Faseeh Ahmad, Konstantinos Chatzilygeroudis, Luigi Nardi, Volker Krueger	1995
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