

2023 WRC Symposium on Advanced Robotics and Automation (WRC SARA 2023)

**Beijing, China
19 August 2023**



**IEEE Catalog Number: CFP23Q58-POD
ISBN: 979-8-3503-0733-7**

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IEEE Catalog Number:	CFP23Q58-POD
ISBN (Print-On-Demand):	979-8-3503-0733-7
ISBN (Online):	979-8-3503-0732-0
ISSN:	2835-3366

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Technical Program

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Fatikow, Sergej	University of Oldenburg
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Co-Chair: Chen, Fei	The Chinese University of Hong Kong
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Yang, Wenhao	Tsinghua University
Chen, Rui	Tsinghua University
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cui, kunkun	Nanjing University of Aeronautics and Astronautics
GUO, AN	Nanjing University of Aeronautics and Astronautics
Wang, Lingyu	Nanjing University of Aeronautics and Astronautics
Bin, YiMing	Nanjing University of Aeronautics and Astronautics
Wan, Minhong	Zhejiang Lab
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Wang, Xin	Zhejiang Lab
Liang, Dingkun	Research Institute of Interdisciplinary Innovation, Zhejiang Lab
Xiong, Jiaming	Peking University
Xie, Anhuan	Zhejiang University
Gu, Jason	Dalhousie University
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Chair: Su, Baiquan	Beijing University of Posts and Telecommunications
Co-Chair: Liu, Wenyong	Beihang University
Organizer: Su, Baiquan	Beijing University of Posts and Telecommunications
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Shen, Hongbin	BeiHang University
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Zhu, Yuanyuan	Beihang University
Zhang, Jian	Beihang University
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Xue, Yumei	Beihang University
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PEI, xu	Beihang University
XIAO, Feng	Beihang University
LI, Wenhao	Beihang University
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Guo, Anyi	Beijing Jishuitan Hospital
liu, yan	Beihang University
Hou, Kedong	Beijing Pinggu District Hospital
Liu, Yajun	Beijing Jishuitan Hospital
Liu, Wenyong	Beihang University
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Yuan, Mengning	Peking University School and Hospital of Stomatology
Jie, Bimeng	Peking University
He, Yang	Peking University School and Hospital of Stomatology
Zhu, Jiayu	Beihang University
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Wang, Junchen	Beihang University
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Shi, Yunze	Zhejiang University
Li, Haoyu	Zhejiang University
Yang, Liangjing	Zhejiang University
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Sheng, Yongji	The University of Hong Kong
Wang, Siyu	The University of Hong Kong
MA, YE	The University of Hong Kong
Kwok, Chun	The University of Hong Kong
Wang, Qingyang	The University of Hong Kong

Xi, Ning	The University of Hong Kong
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Gao, Lifu	Hefei Institutes of Physical Science, Chinese Academy of Science
Cao, Huibin	Institute of Intelligent Machines, Chinese Academy of Sciences
Sun, Yuxiang	Institute of Intelligent Machines, Chinese Academy of Sciences

SaS2B	Room E
Control Methods and Mechatronic Designs towards Higher Level Autonomous Medical Robots 2 (Invited Sessions)	

Chair: Su, Baiquan	Beijing University of Posts and Telecommunications
Co-Chair: Wang, Junchen	Beihang University
Organizer: Su, Baiquan	Beijing University of Posts and Telecommunications

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Hu, Lei	Beihang University
Liu, Wenyong	Beihang University

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Lu, Chunheng	Beihang University
Luo, Xuejin	Beihang University
Wang, Junchen	Beihang University

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Lu, Chunheng	Beihang University
Chen, Chenghao	Beijing Children's Hospital, Capital Medical University
Song, Zhihong	Beihang University
Wang, Junchen	Beihang University

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Deng, Yingyan	Beihang University
Piao, Yang	Peking University School and Hospital of Stomatology
Lu, Chunheng	Beihang University
Bao, Xudong	Peking University School and Hospital of Stomatology
Dong, Yanmei	Peking University School and Hospital of Stomatology
Wang, Junchen	Beihang University

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Chair: Chen, Fei	The Chinese University of Hong Kong
Co-Chair: Li, Qiang	Bielefeld University
Organizer: Wang, Cong	Delft University of Technology (TU Delft)
Organizer: Chen, Fei	Chinese University of Hong Kong
Organizer: Chen, Jianyu	Tsinghua University
Organizer: Li, Gaofeng	Zhejiang University
Organizer: Li, Qiang	Bielefeld University
Organizer: Xie, Ming	Nanyang Technological University
Organizer: Wang, Xin	Chinese University of Hong Kong
Organizer: Ren, Qinyuan	Chinese University of Hong Kong

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Chen, Fei	The Chinese University of Hong Kong

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Liu, Yun	Zhejiang Lab
Huang, Qiulan	ZHEJIANG LAB
Zhang, Pu	Zhejianglab
Yan, Mindong	Zhejiang Lab
Liang, Dingkun	Research Institute of Interdisciplinary Innovation, Zhejiang Lab
Kong, Lingyu	Zhejiang Lab
Wang, Xin	Zhejiang Lab
Xie, Anhuan	Zhejiang University
Gu, Jason	Dalhousie University
Zhu, Shiqiang	Zhejiang Lab

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Cheng, Maotong	Zhejiang University
Zhu, Wenxin	Zhejiang University
Ren, Qinyuan	Zhejiang University

SaS3B Room E
Control Methods and Mechatronic Designs towards Higher Level Autonomous Medical Robots 3 (Invited Sessions)

Chair: Su, Baiquan	Beijing University of Posts and Telecommunications
Co-Chair: Wang, Junchen	Beihang University
Organizer: Su, Baiquan	Beijing University of Posts and Telecommunications

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Luo, Xuejin	Beihang University
Yang, Siqin	Beihang University
Xu, Hao	Beihang University, Beijing
Lu, Chunheng	Beihang University
Wang, Junchen	Beihang University

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Chen, Anqi	Beijing University of Posts and Telecommunications
Ma, Xudong	Beijing University of Posts and Telecommunications
Sun, Yixin	Beijing University of Posts and Telecommunications
Liu, Wenyong	Beihang University
Wang, Junchen	Beihang University
Li, Changsheng	Beijing Institute of Technology
Hu, Yida	Harvard Medical School
Su, Baiquan	Beijing University of Posts and Telecommunications

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Teleoperation of Multi-Functional Neurosurgical Tool, pp. 121-126.

Ma, Xudong	Beijing University of Posts and Telecommunications
Yao, Lechen	The Affiliated High School of Peking University
Chen, Anqi	Beijing University of Posts and Telecommunications
Wang, Junchen	Beihang University
Li, Changsheng	Beijing Institute of Technology
Liu, Wenyong	Beihang University
Hu, Yida	Harvard Medical School
Su, Baiquan	Beijing University of Posts and Telecommunications

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Ma, Xudong	Beijing University of Posts and Telecommunications
Kuang, Ziao	School of Computer Science (National Pilot Software Engineering
Li, Han	Beijing University of Posts and Telecommunications
Chen, Anqi	Beijing University of Posts and Telecommunications
Li, Changsheng	Beijing Institute of Technology
Liu, Wenyong	Beihang University
Wang, Junchen	Beihang University
Hu, Yida	Harvard Medical School

Gao, Li
Su, Baiquan

Peking University School and Hospital of Stomatology
Beijing University of Posts and Telecommunications

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Chair: Qi, Wen		Politecnico Di Milano
Co-Chair: Su, Hang		Politecnico Di Milano
Organizer: Qi, Wen		Politecnico Di Milano
Organizer: Ntalampiras, Stavros		University of Milan
Organizer: Yue, Zhengjun		Technische Universiteit Delft
Organizer: Ovrur, Salih Ertug		Imperial College London
Organizer: Su, Hang		Politecnico Di Milano
Organizer: Chen, Yue		Georgia Institute of Technology
Organizer: Aliverti, Andrea		Department of Electronics, Information and Bioengineering, Polit
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Li, Zhijie		South China University of Technology
Su, Hang		Politecnico Di Milano
Qi, Wen		Politecnico Di Milano
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Li, Yuhan		South China University of Technology
wang, shengzhi		South China University of Technology
Du, Juan		South China University of Technology
Qi, Wen		Politecnico Di Milano
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chen, furong		Changchun University of Science and Technology
Yang, xiaolong		Changchun University of Science and Technology
yong, qi		ESIEE Paris
Dong, Yanling		Shandong University
Zhang, xinming		Changchun University of Science and Technology
zheng, long		Weihai Institute for Bionics, Jilin University
Su, Hang		Politecnico Di Milano
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chen, furong		Changchun University of Science and Technology
wang, feilong		Changchun University of Science and Technology
Yang, xiaolong		Changchun University of Science and Technology
yong, qi		ESIEE Paris
Dong, Yanling		Shandong University
Gao, Yi		Changchun University of Science and Technology
zheng, long		Weihai Institute for Bionics, Jilin University
Su, Hang		Politecnico Di Milano
SaS4B		Room E
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Chair: ji, Daxiong		Zhejiang University
Organizer: ji, Daxiong		Zhejiang University
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ji, Daxiong		Zhejiang University
Xu, Minghui		Zhejiang University
Wang, Xinwei		Zhejiang University
Ye, Zhangying		Zhejiang University

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Zhang, Guoqing	Dalian Maritime University
Huang, Chenfeng	Dalian Maritime University
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ji, Daxiong	Zhejiang University
Cheng, Huifang	Zhejiang University
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Chair: Wei, Junyi	University of Essex
Co-Chair: ZHANG, Tieshan	City University of Hong Kong
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Wang, Fengwu	Beihang University
Zhao, Jiawei	Beihang University, School of Mechanical Engineering and Automati
Wang, Chutian	Beihang University
Li, Chan	Beihang University
Feng, Lin	Beihang University
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Zhao, Jiawei	Beihang University, School of Mechanical Engineering and Automati
Wei, Junyi	University of Essex
Feng, Lin	Beihang University
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ZHANG, Tieshan	City University of Hong Kong
Ren, Hao	City University of Hongkong
LI, Gen	City University of Hong Kong
GUO, DONG	City University of Hong Kong
Shang, Wanfeng	Shenzhen Institutes of Advanced Technology, Chinese Academy of S
Shen, Yajing	The Hong Kong University of Science and Technology
SaR1B	Room E
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Yuan, Shuai	Shenyang Jianzhu University
Yang, Yongliang	Shenyang Institute of Automation, CAS
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Ge, Zhixing	Shenyang Institute of Automation
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[Attachment](#)

Zhou, AIWU
Zhang, Yi

Nanyang Technological University
University of Electronic Science and Technology of China

SaR2A		Room D
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Dai, Yanping	Shenyang Institute of Automation, Chinese Academy of Sciences	
Chen, Wen yuan	Shenyang Institute of Automation, Chinese Academy of Sciences	
Xi, Ning	The University of Hong Kong	
Wang, Wenxue	Shenyang Institute of Automation, CAS	
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Zhu, Haier	Tsinghua University	
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Xiao, Lijun	Hunan University	
Liu, Wei	Hunan University	
yang, zhi	Hunan University	
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yang, zhi	Hunan University	
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Tao, Yong	Beijing University of Aeronautics and Astronautics	
Liu, Xiaonan	Beijing New Materials and New Energy Technology Development Prom	
Song, Yian	Beihang University; School of Mechanical Engineering & Automatio	
GAO, HE	BeiHang University	
SaR2B		Room E
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Gu, Yuqing	Donghua University	
Li, Xiangjian	Donghua University	
Xiao, Xinjie	Donghua University	
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Li, Xiangjian	Donghua University	
Xiao, Xinjie	Donghua University	

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Mingjie, Yao	Qingdao University
Fu, Chaoxing	Qingdao University
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FANG, Baofu	HeFei University of Technology
Pan, Qing	Hefei University of Technology
Wang, Hao	Hefei University of Technology
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Yuan, Shuai	Shenyang Jianzhu University
Wen, Ke	Shenyang Jianzhu University
Zhang, feng	Shenyang Jianzhu University
Xiong, Jianqiang	Shenyang Jianzhu University
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Xiong, Jianqiang	Shenyang Jianzhu University
Yuan, Shuai	Shenyang Jianzhu University
Wen, Ke	Shenyang Jianzhu University
SaR3A	Room D
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Chair: LI, Xiang	Tsinghua University
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LI, Xiang	Tsinghua University
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Li, Deran	Hefei University of Technology
Cao, Jian	Hefei University of Technology
Li, Feiteng	Zhejiang University
Zhu, Xiaocong	Zhejiang University
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Song, Shuaili	Zhejiang University
Gao, Yingying	Zhejiang University
Zhu, Xiaocong	Zhejiang University
Cao, Jian	Hefei University of Technology
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Jiang, Bingshan	Zhejiang Lab
Kong, Lingyu	Zhejiang Lab
Xie, Anhuan	Zhejiang University
Wang, Xin	Zhejiang Lab
Huang, Guanyu	Zhejiang Lab
Zhang, Lan	Zhejiang Lab
Zhao, Pengyu	Zhejiang Lab
Tian, Xinyu	Beijing Jiaotong University
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Cao, Jian	Hefei University of Technology
Xue, Liang	Hefei University of Technology

Zhu, Xiacong
Wang, Shanbo
Han, Shun

Zhejiang University
Hefei University of Technology
Hefei University of Technology

SaR3B		Room E
Intelligent Control (Regular Sessions)		
Chair: Li, Qiang		Bielefeld University
Co-Chair: Xu, Tianbo		Shenyang Jianzhu University
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wang, zhangtao		Beihang University
wu, wenle		Beihang University
wan, yi		Beihang University
Wang, Xingjian		Beihang University
WANG, Shaoping		Beihang University
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Starostenko, Aleksey		Moscow Institute of Physics and Technology
Kozin, Filipp		Moscow Institute of Physics and Technology
Gorbachev, Roman		Moscow Institute of Physics and Technology
Khvostikova, Olga		Moscow Institute of Physics and Technology
Gerasimov, Sergei		Moscow Institute of Physics and Technology
Zakharova, Ekaterina		Moscow Institute of Physics and Technology
Zaripov, Mikhail		Moscow Institute of Physics and Technology
Davydenko, Egor		Moscow Institute of Physics and Technology
Gonnochenko, Aleksei		Sberbank Russia
17:40-17:50		SaR3B.3
<i>Deep Vision Guided Mobile Robot Dual Axis PID Dynamic Real Time Adjustment Following</i> , pp. 316-321.		
Li, Yang		Guizhou University
Yang, Guanci		Guizhou University
He, Ling		Guizhou University
Zhao, Le		Guizhou University
Zhao, Tianyi		Guizhou University
Sun, Haoran		Guizhou University
17:50-18:00		SaR3B.4
<i>Passivity Analysis for Singular Semi-Markovian Jump Systems Based on T-S Fuzzy Model</i> , pp. 322-328.		
Xu, Tianbo		Shenyang Jianzhu University
Jin, Meixi		Shenyang Jianzhu University, No. 25, Middle Hunnan Road, Hunnan
Qi, Wenhai		Qufu Normal University
Wang, Jin		Shenyang Jianzhu University
SaPP		Hall
Poster Session (Poster Sessions)		
Chair: XIU, WEI		Chinese Institute of Electronics
14:00-18:00		SaPP.1
<i>Research on Feature Point Localization Technology Based on Binocular Vision</i> , pp. 329-334.		
Liu, Lei		University of Jinan
Jun, Wei		University of Jinan
Mu, Qingsheng		University of Jinan
14:00-18:00		SaPP.2
<i>Towards Autonomous Robotic Ultrasound Scanning Using the Reinforcement Learning-Based Volumetric Data Navigation Method</i> , pp. 335-340.		
Shen, Cuifeng		Institute of Automation, Chinese Academy of Sciences
Deng, Zhaokun		Institute of Automation, Chinese Academy of Sciences
Wang, Jinzhi		College of Engineering, Peking University
Wang, Shuangyi		Chinese Academy of Sciences

Chen, Chen	Institute of Automation, Chinese Academy of Sciences
14:00-18:00	SaPP.3
<i>Towards Automated Ultrasound Scanning Using Vision-Based Navigation: From Physician Skill Learning to Robotic Reproduction</i> , pp. 341-346.	
Hao, Mingrui	Institute of Automation, Chinese Academy of Sciences
Zhang, Pengcheng	Institute of Automation, Chinese Academy of Sciences
Chen, Chen	Institute of Automation, Chinese Academy of Sciences
Wang, Shuangyi	Chinese Academy of Sciences
14:00-18:00	SaPP.4
<i>Research on Absolute Positioning Error Compensation of Serial 6-DOF Industrial Robot (I)</i> , pp. 347-352.	
Cui, Rongyue	University of Jinan
Jun, Wei	University of Jinan
Liang, Liang	SIASUN Robot & Automation CO., Ltd
14:00-18:00	SaPP.5
<i>Research on Capacitance Compensation for Temperature Changes in Laser Cutting Systems (I)</i> , pp. 353-358.	
Hu, Jingru	University of Jinan
Jun, Wei	University of Jinan
Luan, Xianye	Shandong SIASIN Industrial Software Research Institute Co., Ltd
Gong, Fei	Shandong SIASIN Industrial Software Research Institute Co., Ltd
14:00-18:00	SaPP.6
<i>Aircraft Skin Seam Location and Step Difference Measurement Based on 3D Point Cloud</i> , pp. 359-364.	
Yu, Haiwen	Nanjing University of Aeronautics and Astronautics
Chen, Bai	Nanjing University of Aeronautics and Astronautics
Duan, Jinjun	Nanjing University of Aeronautics and Astronautics
Ding, Liping	Nanjing University of Aeronautics and Astronautics
14:00-18:00	SaPP.7
<i>Design and Implementation of a New Spherical Robot with an Elastic Pawl</i> , pp. 365-370.	
Fang, Shihao	Beijing University of Civil Engineering and Architecture
qin, jianjun	Beijing University of Civil Engineering and Architecture
Cao, Yu	Beijing University of Civil Engineering and Architecture
Shao, Pai	Beijing University of Civil Engineering and Architecture
14:00-18:00	SaPP.8
<i>Development and Kinematic Accuracy Analysis of Supernumerary Robotic Limbs</i> , pp. 371-376.	
Liao, Ziyu	NUAA
Chen, Bai	Nanjing University of Aeronautics and Astronautics
Zheng, Qian	Nanjing University of Aeronautics and Astronautics
Xu, Jiajun	Nanjing University of Aeronautics and Astronautics
Tu, Zhendong	Nanjing University of Aeronautics and Astronautics
Wu, Hongtao	Nanjing University of Aeronautics and Astronautics
14:00-18:00	SaPP.9
<i>Research on Tail Gas Optimization Method Based on Adaptive Dynamic Programming</i> , pp. 377-382.	
Song, Xue	Changchun University of Science and Technology
Yang, Yang	Changchun University of Science and Technology
Song, Yaru	Changchun University of Science and Technology
Li, Mingqiu	Changchun University of Science and Technology
14:00-18:00	SaPP.10
<i>Trajectory Planning of Robot End-Effector Position and Orientation Based on Cubic Spline</i> , pp. 383-389.	
Liu, Yang	Northeastern University
Du, Zhenjun	SIASUN Robot & Automation
Liu, Mingmin	SIASUN Robot & Automation
Tao, Tao Yongliang	Northeastern University
Li, Chengpeng	SIASUN Robot & Automation
14:00-18:00	SaPP.11
<i>A Human-Machine Interactive Simulation Environment for Intelligent Analysis of Human Factors Reliability</i> , pp. 390-395.	
wang, chunlei	Shanghai University
wang, xiao	Shanghai University

14:00-18:00	SaPP.12
<i>Dynamic Modeling of the Hybrid Manipulator</i> , pp. 396-401.	
Chen, Weifeng	Tianjin University
Liu, Haitao	Tianjin University
Li, Guangxi	Tianjin University
Bai, Yujie	Tianjin University
14:00-18:00	SaPP.13
<i>An Approach for Upper Limb Movement Intention Recognition Using EEG and sEMG Fusion Based on the MCPSA-CIIM</i> , pp. 402-407.	
Zhang, Weiming	Xi'an Jiaotong University
Zhang, Xiaodong	Xi'an Jiaotong University
Xu, Cheng	Science and Technology on Complex System Control and Intelligent
Zhou, Guchuan	Science and Technology on Complex System Control and Intelligent
Zhang, Teng	Xi'an Jiaotong University
Wang, Yu	Xi'an Jiaotong University
14:00-18:00	SaPP.14
<i>Research on Dermatological Classification Algorithm Based on the Fusion Model</i> , pp. 408-413.	
Zhang, Chenjie	Changchun University of Science and Technology
Wang, Shuai	Changchun University of Science and Technology
Zhang, Yu	Changchun University of Science and Technology
Hu, Hanping	Changchun University of Science and Technology
14:00-18:00	SaPP.15
<i>Garbage Image Classification Algorithm Based on Swin Transformer</i> , pp. 414-419.	
Hu, Hanping	Changchun University of Science and Technology
Wang, Shuai	Changchun University of Science and Technology
Zhang, Chenjie	Changchun University of Science and Technology
Pan, Yue	Changchun University of Science and Technology
14:00-18:00	SaPP.16
<i>Magnetically Controlled Nanorobotic Swarm for the Glioma Therapy</i> , pp. 420-425.	
Li, Chan	Beihang University
HU, Zihan	Beijing University of Aeronautics and Astronautics
Sun, Hongyan	Beihang University
Wang, Chutian	Beihang University
Zeng, Zijin	Beihang University
Feng, Lin	Beihang University
14:00-18:00	SaPP.17
<i>Multi-Class Industrial Texture-Less Object Detection Method in Cluttered and Occluded Scenes</i> , pp. 426-431.	
Li, Sicong	Shenyang Institute of Automation, Chinese Academy of Sciences
Zhu, Feng	Shenyang Institute of Automation, Chinese Academy of Sciences
Wu, Qingxiao	Shenyang Institute of Automation Chinese Academy of Sciences
14:00-18:00	SaPP.18
<i>A New CCA-Based Method for Improving SSVEP-Based BCI System Classification</i> , pp. 432-437.	
Cui, Yingxue	Zhengzhou University of Light Industry
14:00-18:00	SaPP.19
<i>Deep Learning Based Defect Detection Algorithm for Solar Panels</i> , pp. 438-443.	
Li, Jiaqi	University
Li, Hongxu	Yanshan University
Wu, Yifan	University of Alberta
Zhou, Hailiang	Hebei Baoding Jiasheng Photovoltaic Technology Co., Ltd
Manfredi, Luigi	University of Dundee
Li, Peng	Yanshan University
Zhang, Hong	University of Alberta
14:00-18:00	SaPP.20
<i>Event-Potential Method for Mobile Robot Motion Planning and Control</i> , pp. 444-450. Attachment	
Sheng, Yongji	The University of Hong Kong
Ye, Jiajie	The University of Hong Kong

Wang, Siyu	The University of Hong Kong
Liu, Xinyu	The University of Hong Kong
Xi, Ning	The University of Hong Kong
14:00-18:00	SaPP.21
<i>Kinematics Solution of Cable-Driven Parallel Robots Considering Cable Sagging (I)</i> , pp. 451-458.	
Gao, Feng	University of Science and Technology of China
Gao, Lifu	Hefei Institutes of Physical Science, Chinese Academy of Science
Wang, Daqing	Hefei Institutes of Physical Science, Chinese Academy of Science
Jiang, Man	Hefei Institutes of Physical Science, Chinese Academy of Science
14:00-18:00	SaPP.22
<i>Modeling and Simulation of Submarine Launched UAV Formation and Formation Reconfiguration with Initial Discrete (I)</i> , pp. 459-464.	
Jia, Huayu	University of Chinese Academy of Sciences
Zheng, HuiLong	University of Chinese Academy of Sciences
Zhou, Hong	University of Chinese Academy of Sciences
Zhang, Qian	University of Chinese Academy of Sciences
Li, XinSong	Shenyang Aerospace University
14:00-18:00	SaPP.23
<i>Edge Detection and Alignment Control Method for Mobile Robots Based on Multi-Lidar Fusion</i> , pp. 465-472.	
GAO, HE	BeiHang University
Tao, Yong	Beijing University of Aeronautics and Astronautics
Liu, Xiaonan	Beijing New Materials and New Energy Technology Development Prom
Zhang, Yufan	Beihang University
Liu, Haitao	BUAA
Wan, Jiahao	Beihang University
14:00-18:00	SaPP.24
<i>Toward Safe Human-Robot Interaction: More Efficient Safety Monitoring Technology for Robotic Arms (I)</i> , pp. 473-478.	
Gong, Zihang	YanTaiUniversity
Liu, Zhaowei	School of Computer and Control Engineering, Yantai University
Su, Hang	Politecnico Di Milano
14:00-18:00	SaPP.25
<i>A Novel Dynamic Motion Planning Based on Error Tolerance Batch Informed Tree</i> , pp. 479-483.	
Cao, Zhimin	Suzhou City University
14:00-18:00	SaPP.26
<i>Gait Planning and Motion Control Based on Vrep Simulation for Quadruped Robot (I)</i> , pp. 484-489.	
zhou, linqi	Nanchang Hangkong University
Chen, Zhihua	Nanchang Hangkong University, Beijing Institute of Technology
Liu, Jun	Nanchang Hangkong University
Liu, Zhi	Beijing Institute of Technology
chen, yumeng	Nanchang Hangkong University
Zhang, Liting	Nanchang Hangkong University
14:00-18:00	SaPP.27
<i>Motion Planning and Tracking Control Method Based on CoppeliaSim for UGV in Irregular Terrain (I)</i> , pp. 490-495.	
Huang, Jiale	School of Information Engineering, Nanchang Hangkong University
Chen, Zhihua	Nanchang Hangkong University, Beijing Institute of Technology
Zhong, Yongbo	Nanchang Hangkong University
Zeng, Wenrui	Nanchang Hangkong University
Ji, Chuanmin	NCHU
14:00-18:00	SaPP.28
<i>Embroidery Robotics: An Innovative Approach to AI-Based Online Learning and Image Generation (I)</i> , pp. 496-503.	
Chen, Ling	Hunan Normal University
Zhang, Tianxin	Hunan Normal University
Chen, Jing	Hunan Normal University
14:00-18:00	SaPP.29
<i>A Fuzzy Inference System on Probabilistic Roadmap for Multi-Robot Path Planning</i> , pp. 504-509.	
Replogle, Brandon	California Polytechnic State University, San Luis Obispo
Yu, Xiao-Hua	California Polytechnic State University, San Luis Obispo

14:00-18:00	SaPP.30
<i>Study on the Grinding Speed Model of Eccentric Shaft Components of the RV Reducer for Robotic Arm</i> , pp. 510-513.	
Jiang, Zhemin	Beijing Beikai Electric Co
fang, haicheng	Beijing Beikai Electric Co
li, chao	Beijing Beikai Electric Co
liu, shilei	Beijing Beikai Electric Co
14:00-18:00	SaPP.31
<i>An Event-Driven Asynchronous Feature Tracking Method (I)</i> , pp. 514-519.	
Xu, Haidong	Soochow University
Jin, Shizhao	Soochow University
Yu, Shumei	Soochow University
Sun, Rongchuan	Soochow University
Sun, Lining	Soochow University
14:00-18:00	SaPP.32
<i>Design of an Impact-Resistant Elbow Mechanism for Wheel-Legged Robot Crawling</i> , pp. 520-525.	
Ma, XS	Beijing Institute of Technology
Gao, Junyao	Beijing Institute of Technology
Qiu, Xuejian	Beijing Institute of Technology
Zhao, Lingxuan	Beijing Institute of Technology
Chen, Xuechao	Beijing Insititute of Technology
YU, Zhangguo	Beijing Institute of Technology
Huang, Qiang	Beijing Institute of Technology
14:00-18:00	SaPP.33
<i>Movement Primitives with Explicit Constraints for Imitation Learning of Pick-And-Place Action</i> , pp. 526-533. Attachment	
Dong, Yue	Beijing Institute of Technology
YU, Zhangguo	Beijing Institute of Technology
Chen, Xuechao	Beijing Insititute of Technology
Wang, Chenzheng	Beijing Insititute of Technology
Huang, Qiang	Beijing Institute of Technology
14:00-18:00	SaPP.34
<i>Depth Control of Cable Patrol Autonomous Underwater Vehicle Based on Reinforcement Learning (I)</i> , pp. 534-540.	
Zhang, Yuenan	Hangzhou Dianzi University
Zhang, Xueting	Hangzhou Dianzi University
Zeng, Fanzong	Hangzhou Dianzi University
Sun, Shangwei	Hangzhou Dianzi University
liu, jingbiao	Hangzhou Dianzi University
zhou, zhe fang	Hangzhou Dianzi University
Guo, Chenhang	Hangzhou Dianzi University
Wang, Dongrui	Hangzhou Dianzi University
14:00-18:00	SaPP.35
<i>Developing a Comprehensive Model for the Prevention of Tension Neck Syndrome: A Focus on Musculoskeletal Disorder Prevention Strategies</i> , pp. 541-548.	
Sohani, Behnaz	University of Lincoln
Adigun, Ifeoluwa Joshua	University of Lincoln
Aliyu, Aliyu	University of Lincoln
Rahmani, Amir	Castlet Ltd
Goher, Khaled	University of Nottingham